



**Several stories about tripeptides:**  
basic components for modeling flexible protein structures

**LAAS**  
**CNRS**



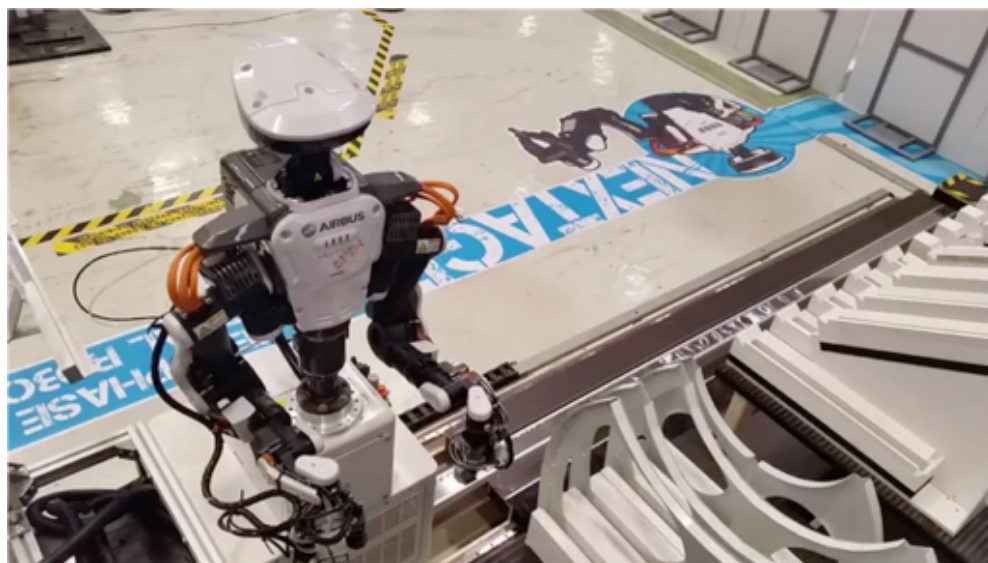
Juan Cortés

BSC - Barcelona, January 2020

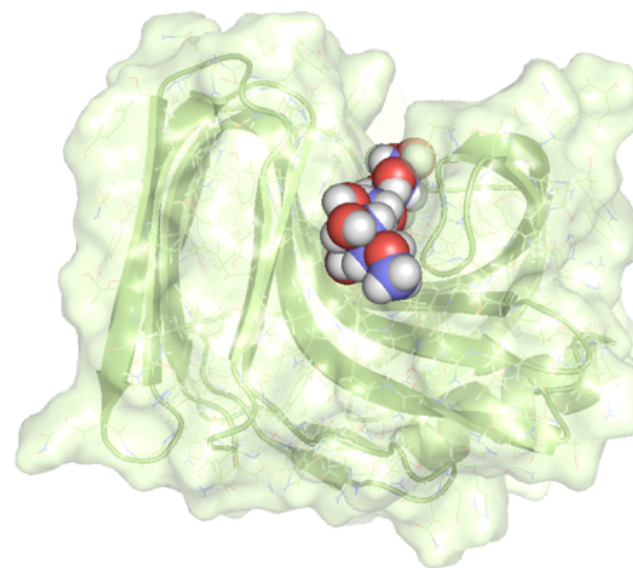
Once upon a time ...

[Cortés *et al.*, *J Comput Chem*, 2004]

From **robot** motion planning...



... to **protein** loop modeling



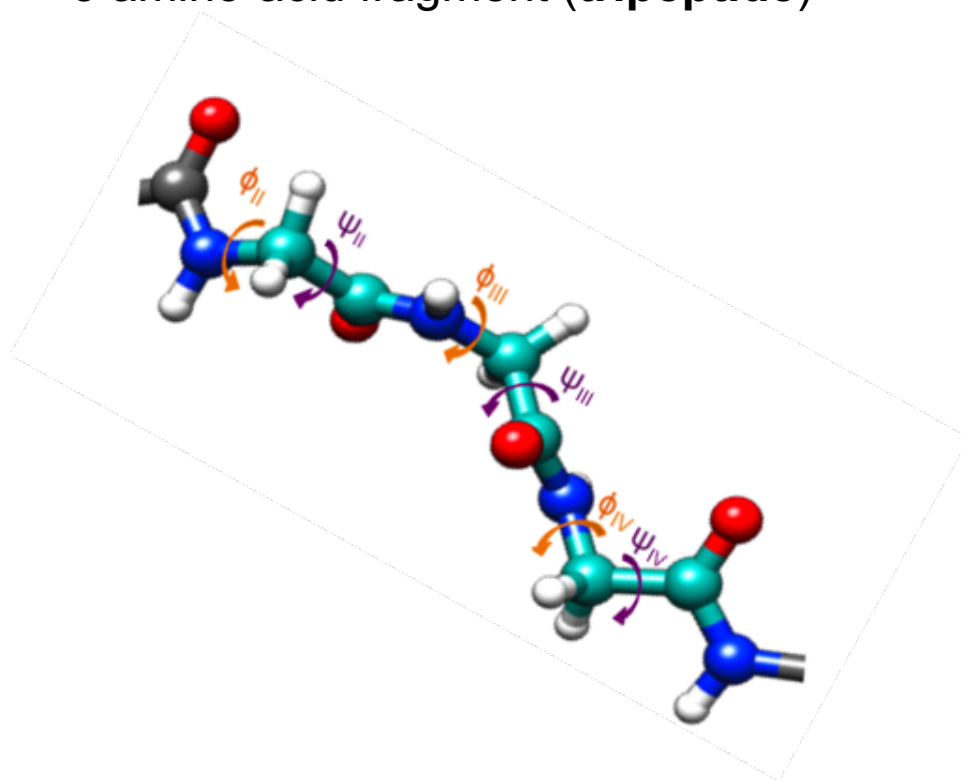
**tripeptides** are a clear link between the two domains

# Tripeptides as basic mechanistic components

Robotic arm (**6R mechanism**)

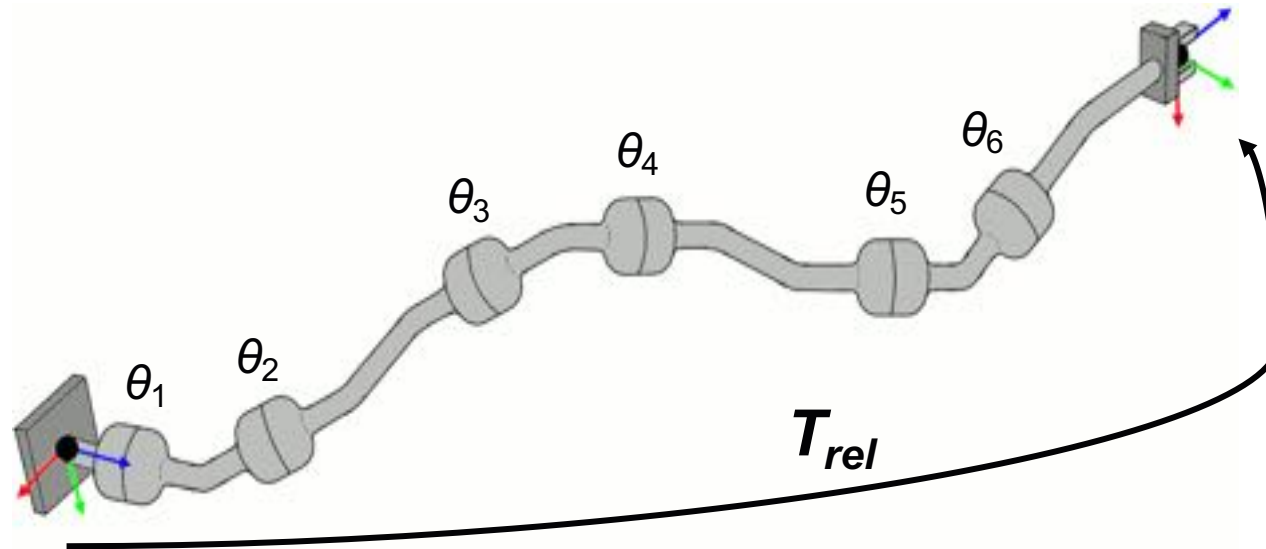


3 amino-acid fragment (**tripeptide**)



6 degrees of freedom : minimum number for full mobility

## The Inverse Kinematics (IK) Problem



Given the relative pose  $T_{rel}$  of the *end-effector* with respect to the *base-frame* find the values of the joint variables  $\theta_i$

$$T_{rel} = {}^0T_1(\theta_1) {}^1T_2(\theta_2) {}^2T_3(\theta_3) {}^3T_4(\theta_4) {}^4T_5(\theta_5) {}^5T_6(\theta_6)$$

→ **Efficient closed-form solvers** [Renaud, 2000]

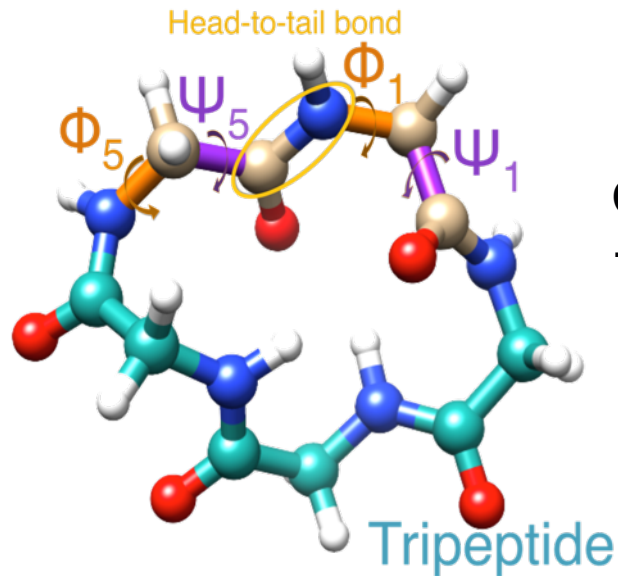


# “Straightforward” application: Sampling of small cyclic peptides

[Jusot *et al.*, JCIM 2018]

*Joint work with J. Chomilier and D. Stratmann (Sorbonne U., Paris)*

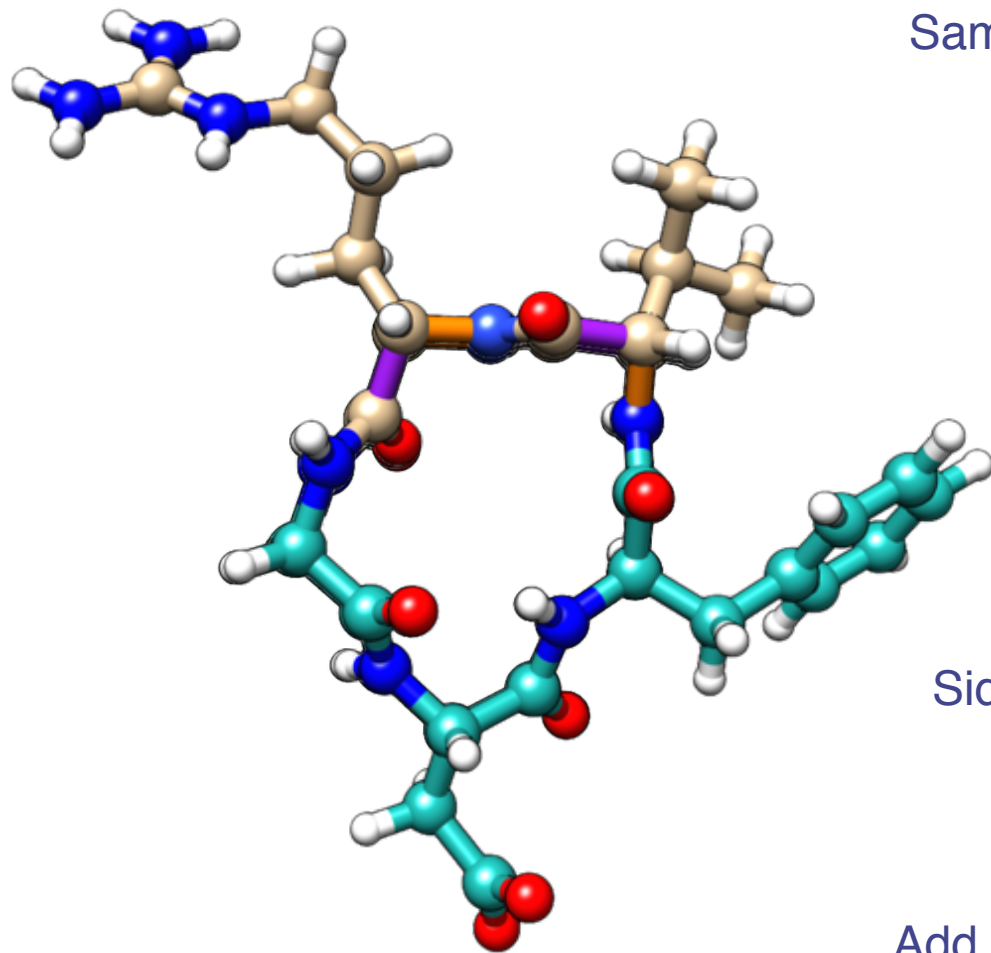
## Cyclic-pentapeptide



Conformational space (considering only  $\Phi$ ,  $\Psi$ )  
→ 4-dimension manifold in a 10-dimension space  
**Can be sampled exhaustively !**

# “Straightforward” application: Sampling of small cyclic peptides

[Jusot *et al.*, JCIM 2018]



Sampling of  $\Phi_1$ ,  $\Psi_1$ ,  $\Phi_5$ ,  $\Psi_5$  (+ all  $\omega$ )



Inverse kinematics:

- 0 solution
- 1 to 16 solutions



Check collisions



Side chains addition(SCWRL)



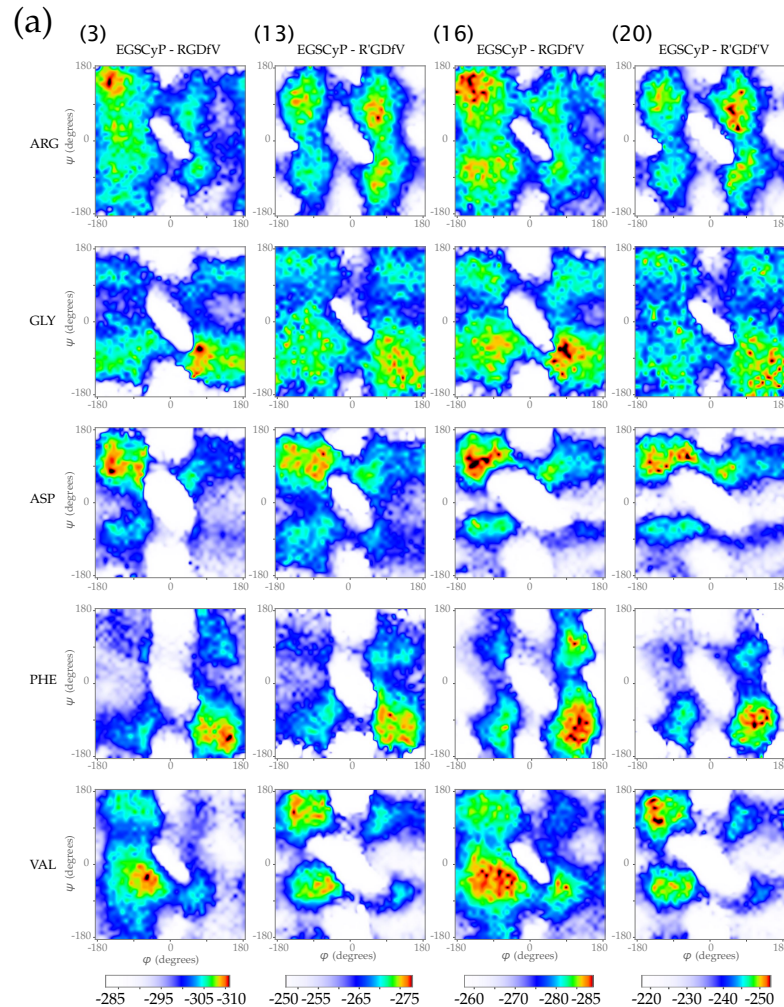
Relaxation (Amber)

Add node to adjacency graph

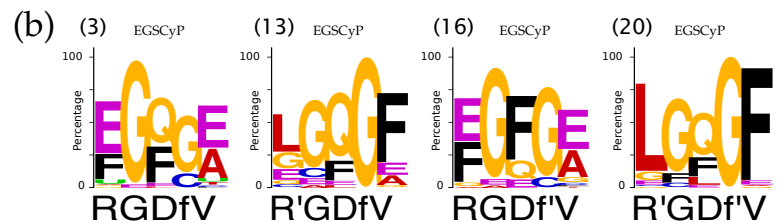


# “Straightforward” application: Sampling of small cyclic peptides

[Jusot *et al.*, JCIM 2018]

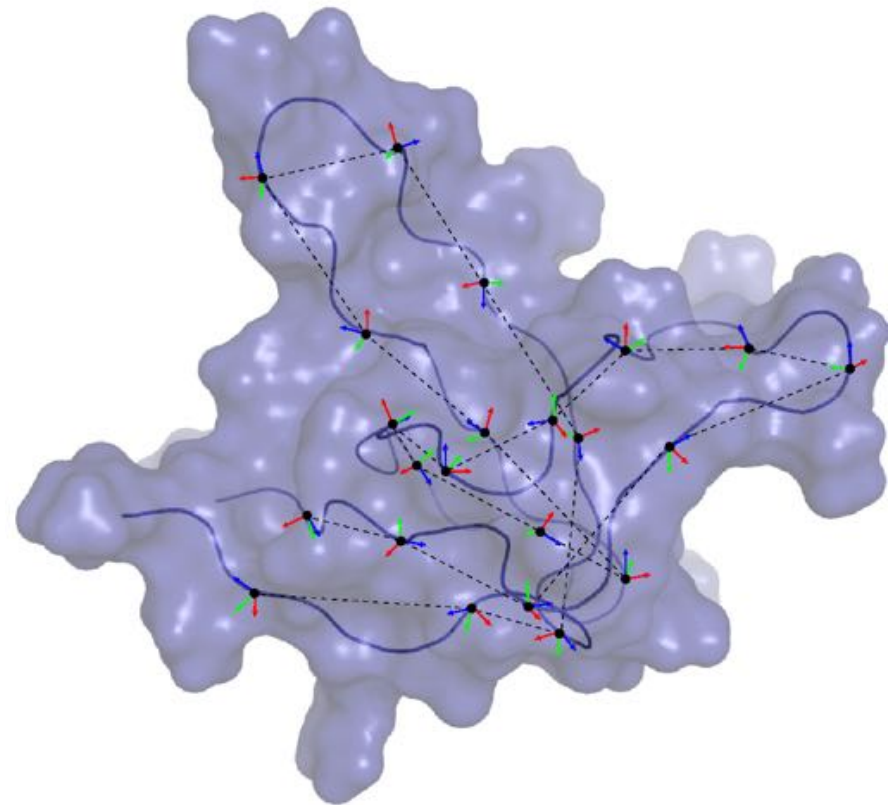


- Analysis of the effect of chemically-modifications or D amino acids
- Potential applications for drug design



## Conformational sampling using the tripeptide-based model

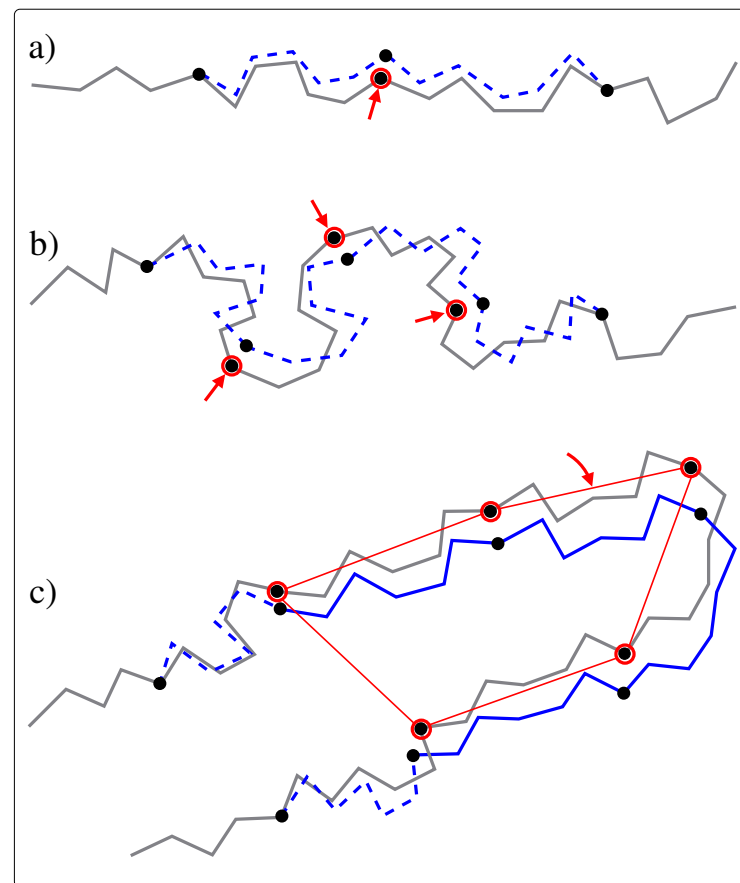
1. Sample/perturb the pose of the base-frame of tripeptides (*oriented particles*)  
→ Coarse-grained model
1. Solve **IK** for tripeptides  
Semi-analytical solver  
(adapted from [Renaud, 2000])  
→ All-atom model



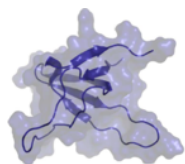


## Local (fixed-end) backbone perturbation methods

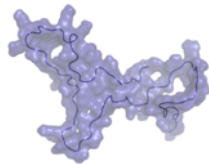
- **One particle moves**
  - Perturb one particle
  - IK for two tripeptides
  - Similar to ConRot [Dodd *et al.*, 1993]
- **Flexible fragment moves**
  - Perturb  $n$  consecutive particles
  - IK for  $n+1$  tripeptides
  - Similar to CCL [Canutescu *et al.*, 2003]
- **Rigid-body block moves (“hinge”)**
  - Perturb  $n$  particles as a rigid-body
  - IK for two tripeptides
  - Similar to CRRUBAR [Betancourt, 2005]



# Tripeptide-based Monte Carlo move classes

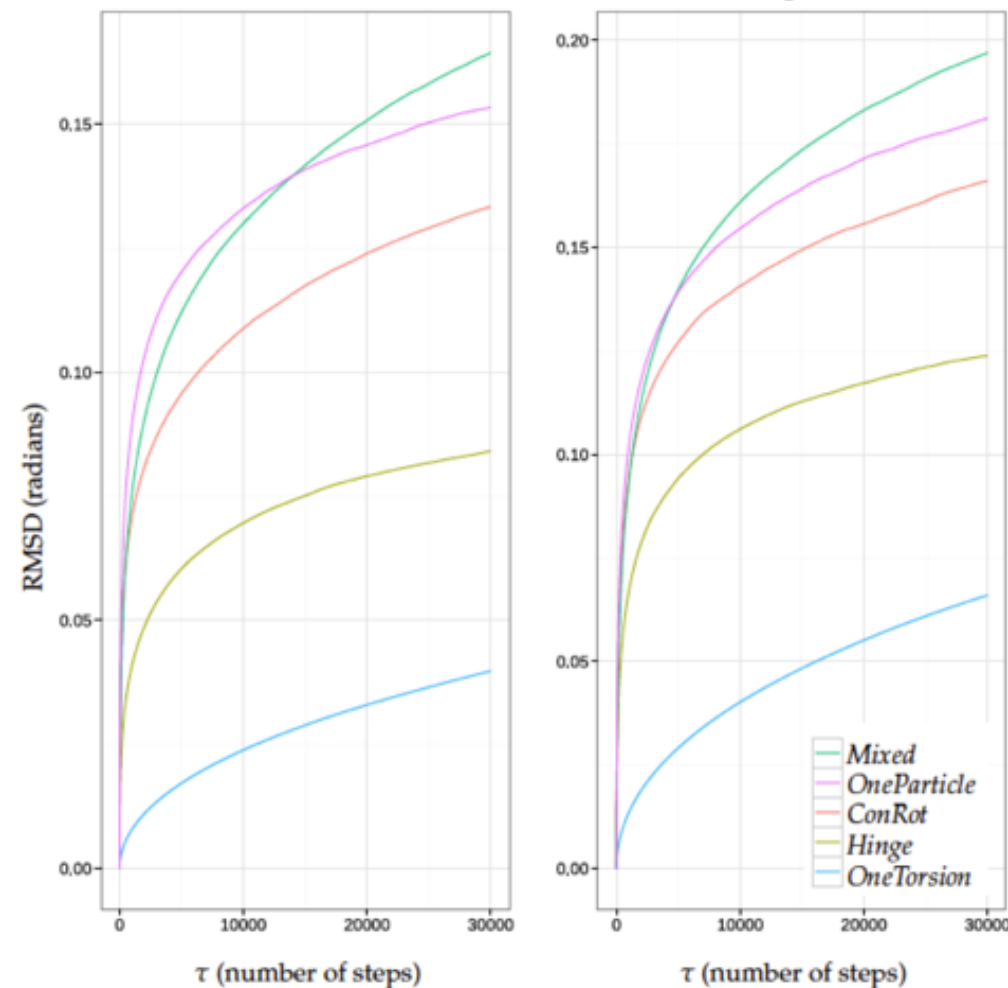


SH3 domain



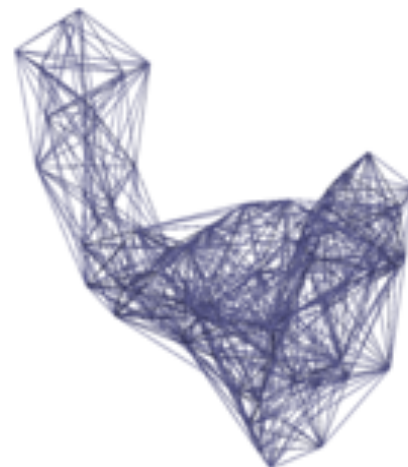
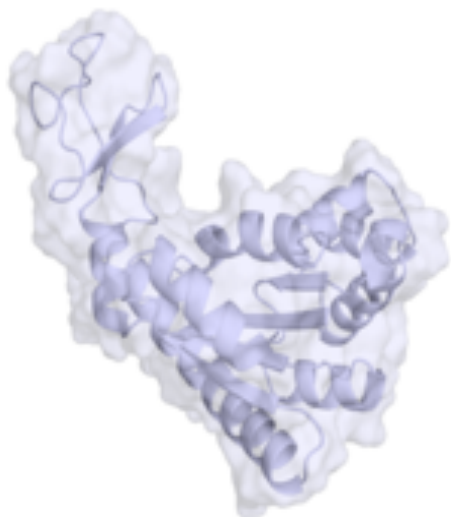
Sic1 protein

[Denarie *et al.*, *Molecules* 2018]



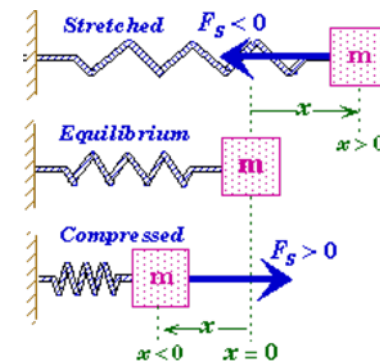
- Fixed-ends moves perform better than classical *pivot* moves
- *Mixing* moves (easy thanks to the tripeptide-based decomposition) outperforms individual moves

## Tripeptide-based Elastic Network Model



- **Topological** force field  
Springs between particles

$$V(x) = \frac{1}{2}k(x - x_0)^2$$



## Tripeptide-based Elastic Network Model



- Diagonalization of the Hessian matrix :
  - Eigenvectors  $\rightarrow$  Vibration directions
  - Eigenvalues  $\rightarrow$  Vibration frequencies
- Low-frequency modes  $\rightarrow$  collective motions

$$\mathbf{H} = \begin{pmatrix} \left( \frac{\partial^2 V}{\partial r_1 \partial r_1} \right)_0 & \left( \frac{\partial^2 V}{\partial r_1 \partial r_2} \right)_0 & \cdots & \left( \frac{\partial^2 V}{\partial r_1 \partial r_{3N}} \right)_0 \\ \left( \frac{\partial^2 V}{\partial r_1 \partial r_2} \right)_0 & \left( \frac{\partial^2 V}{\partial r_2 \partial r_2} \right)_0 & \cdots & \left( \frac{\partial^2 V}{\partial r_2 \partial r_{3N}} \right)_0 \\ \vdots & \vdots & \ddots & \vdots \\ \left( \frac{\partial^2 V}{\partial r_1 \partial r_{3N}} \right)_0 & \cdots & \cdots & \left( \frac{\partial^2 V}{\partial r_{3N} \partial r_{3N}} \right)_0 \end{pmatrix}$$



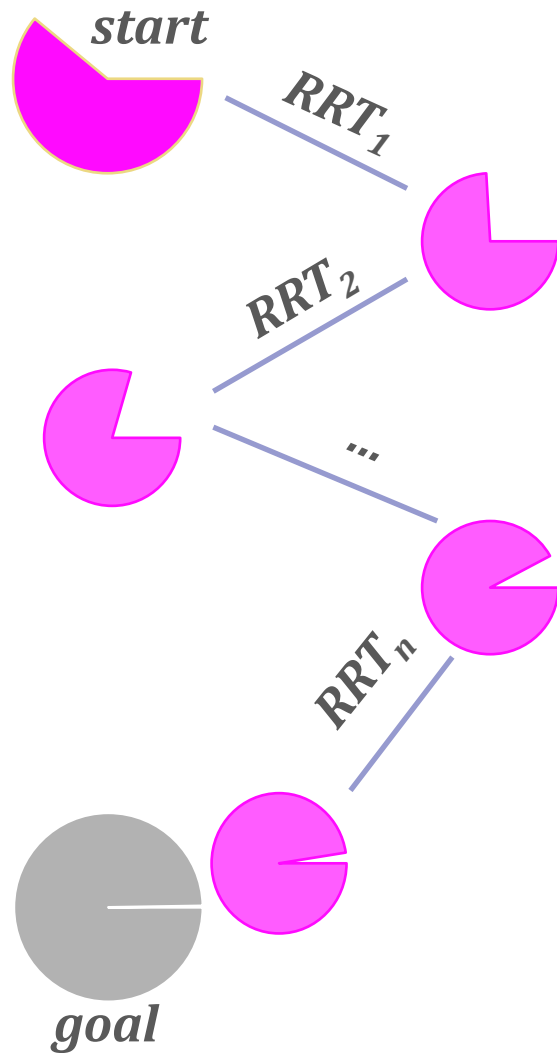
## Tripeptide-based Elastic Network Model



- Advantages :
  - Reduces the size of the hessian matrix by a factor of 3 (compared to  $C\alpha$ -ENM)
  - Preserves the full flexibility of the protein (compared to rigid-block approaches)

# Application : Sample Conformational Transition Pathways

[Al-Bluwi *et al.*, BMC Struct Biol, 2013]



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## Algorithm 1: COMPUTE\_PATHWAY

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**input** : Initial conformation  $q_{init}$ , final conformation  $q_{goal}$  and minimum distance to target  $d_{target}$

**output** : The transition pathway  $p$

**begin**

$q_{root} \leftarrow q_{init};$

**while**  $RMSD(q_{root}, q_{goal}) > d_{target}$  **do**

$m \leftarrow COMPUTE\_NORMALMODES(q_{root});$

$t \leftarrow BUILD\_RRT(m, q_{root}, q_{goal});$

$q_{close} \leftarrow CLOSESTTOTARGET(t, q_{goal});$

$q_{root} \leftarrow MINIMIZE(q_{close});$

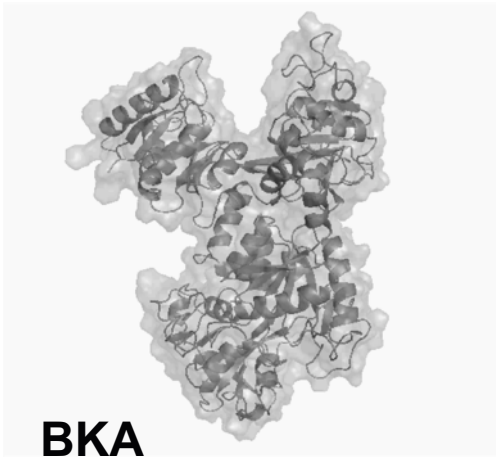
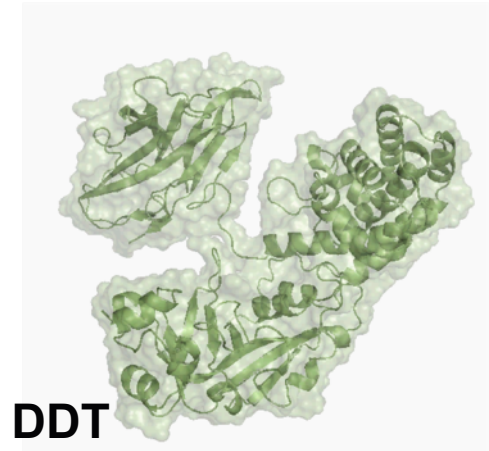
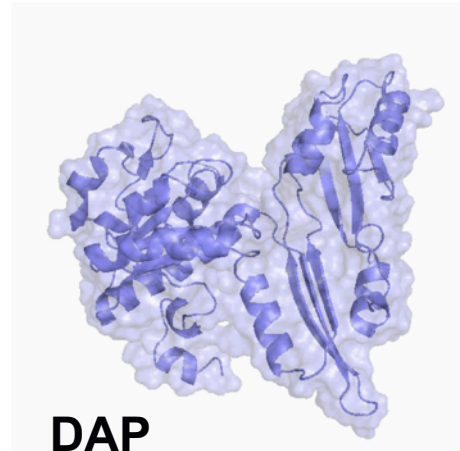
$p \leftarrow CONCATENATE(p, q_{root});$

**end**

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# Application : Sample Conformational Transition Pathways

[Al-Bluwi *et al.*, BMC Struct Biol, 2013]

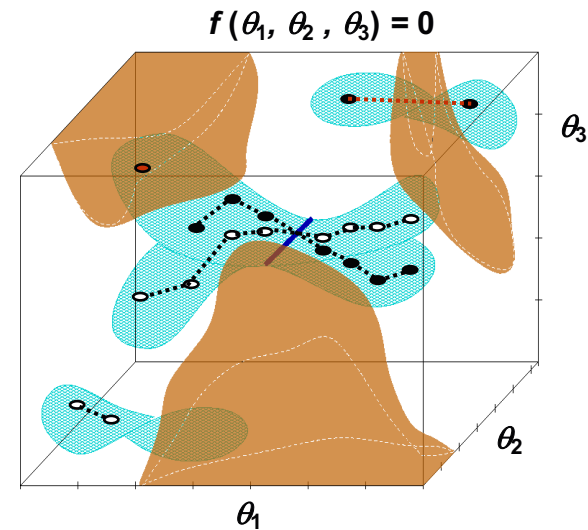


- Single-core CPU time : 2 hours – 2 days (*can be further improved*)

## Challenging problem



## How to sample submanifolds?



## Several approaches:

- **Optimization-based: Coordinate Cyclic Descent (CCD)** [Welman, 1993]
  - Application to proteins: [Canutescu et al, *Protein Sci.*, 2003]
- **Semi-analytical: Random Loop Generator (RLG)** [Cortés et al, 2002]
  - Application to proteins: [Cortés et al, *J. Comput. Chem.*, 2004]



# Sampling Long Protein Loops: *Our first approach*

[Cortés et al., *J Comput Chem*, 2004]

## Random Loop Generator (RLG)

### Main Chain (Backbone)

→ Independent sub-chain

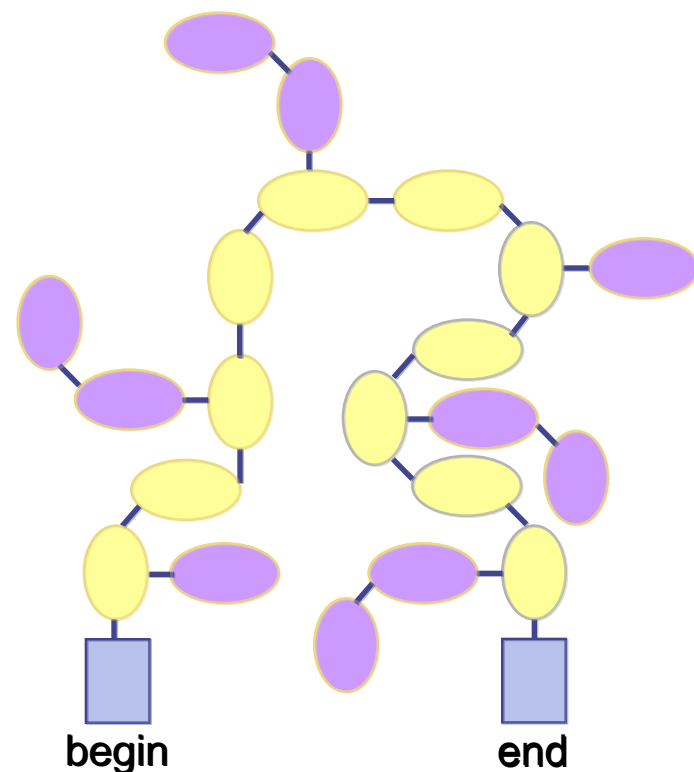
- RLG algorithm + CollCheck

→ Dependent sub-chain

- General 6R IK + CollCheck  
[Renaud, 2000]

### Side Chains

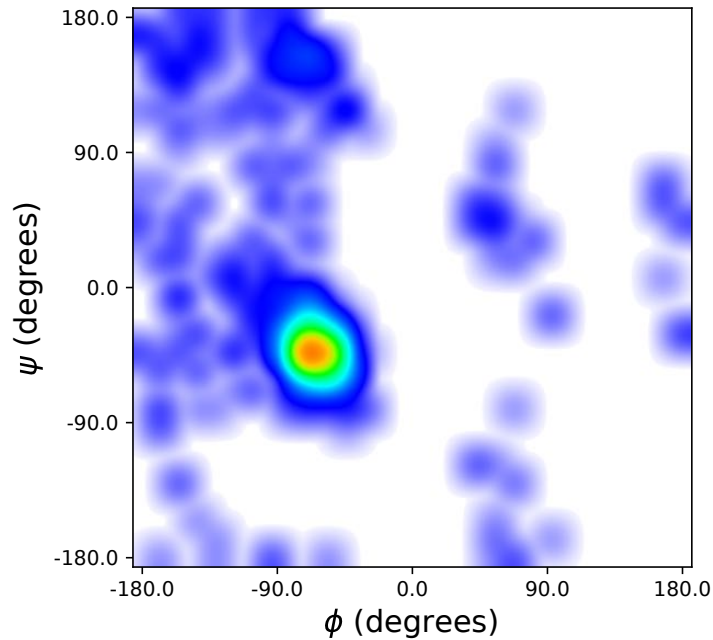
- Random Sampling + CollCheck



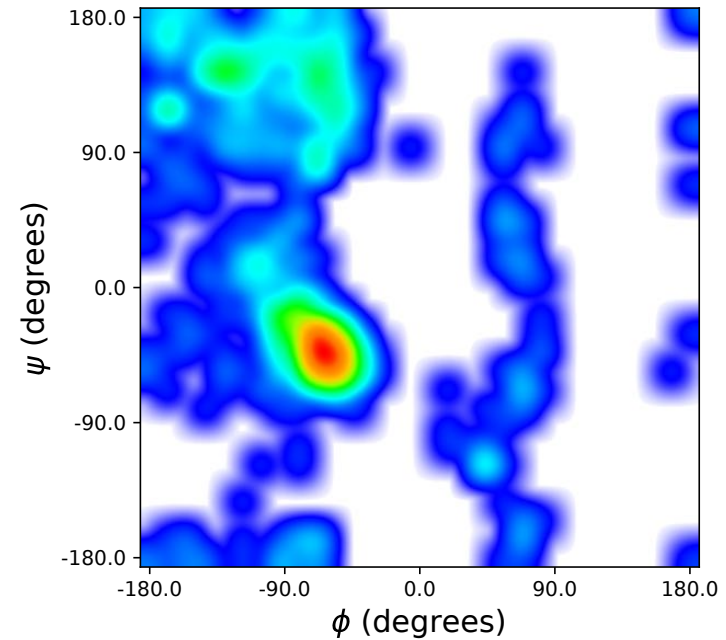
**Residues sampled individually** (excepting for the last tripeptide subject to IK)

## Local sequence matters

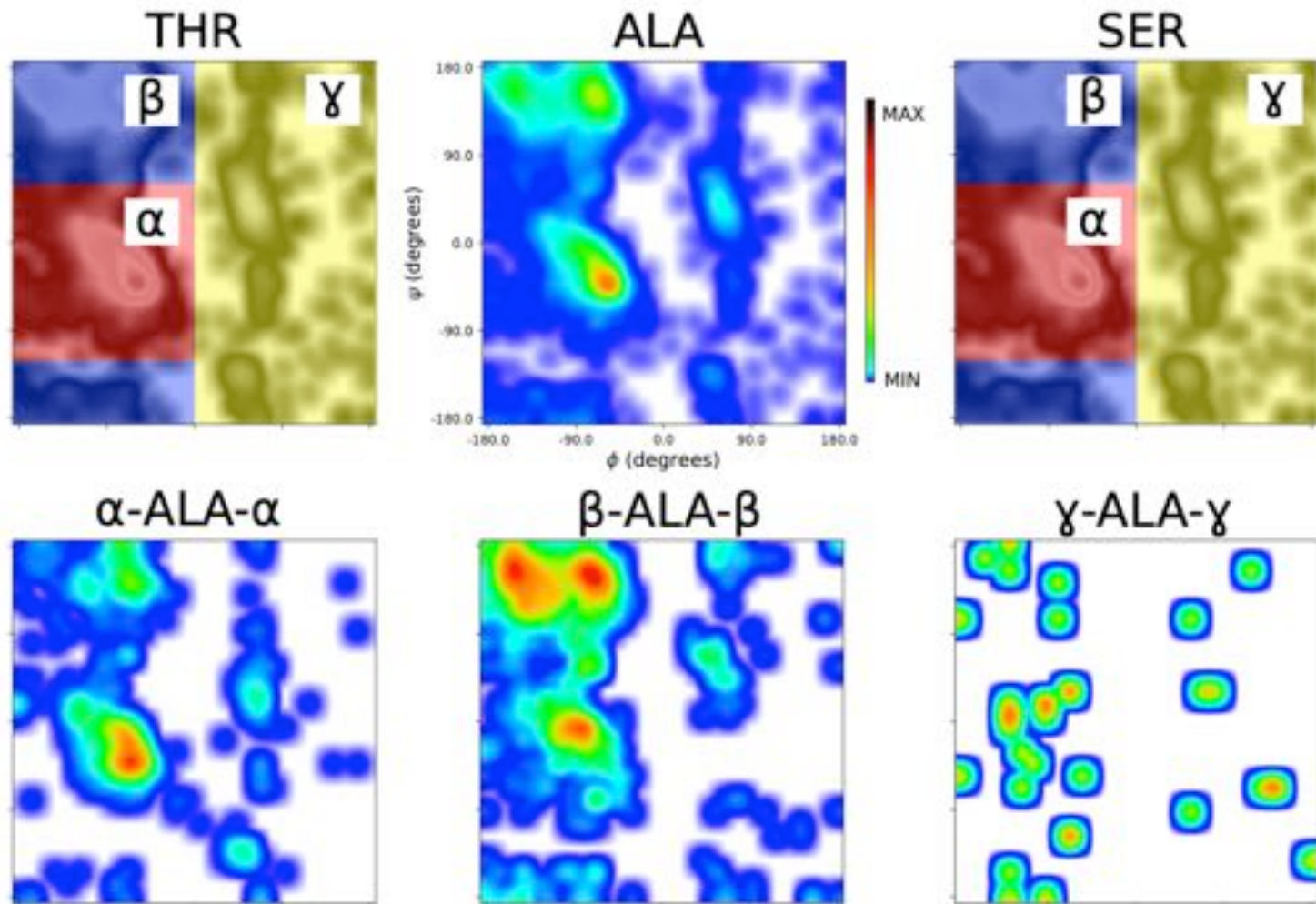
ALA-ALA-ALA



ALA-ALA-GLU

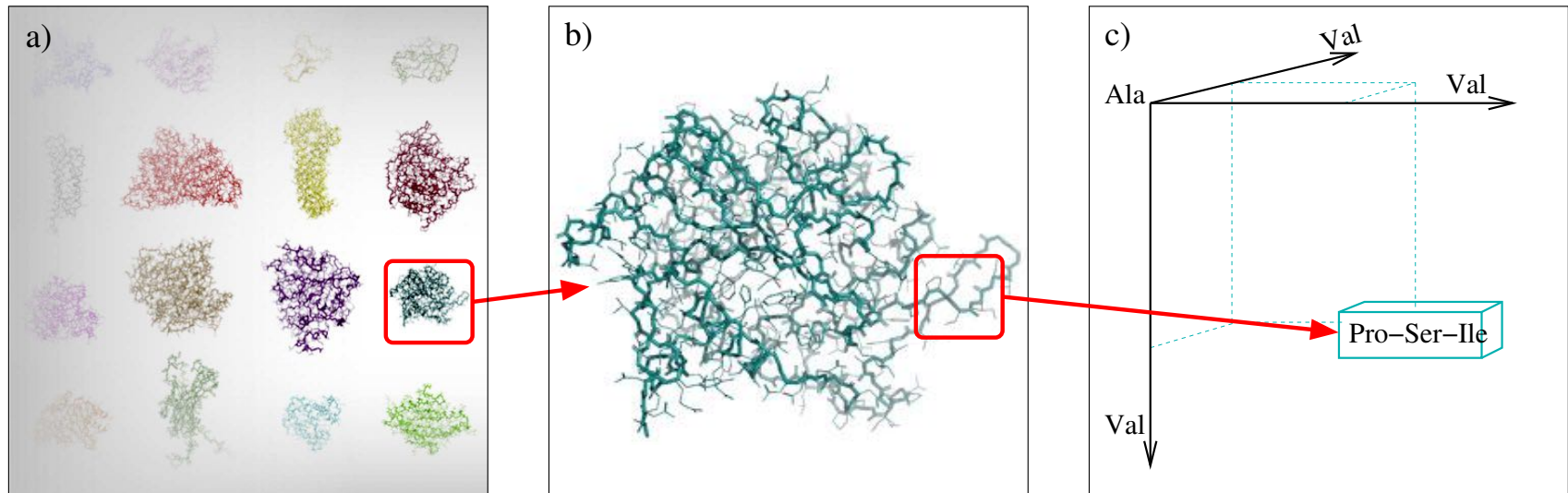


## Local structure matters



## Tripeptide conformations from experimentally-determined high-resolution protein structures

➔ Extracted from SCOPe 95% identity





## Tripeptide conformations from experimentally-determined high-resolution protein structures

→ Extracted from SCOPe - 95% identity

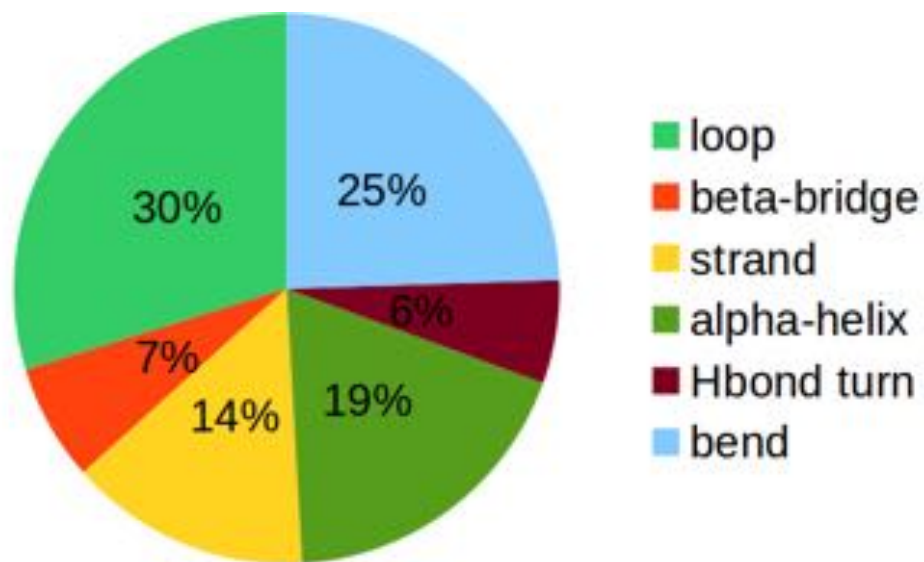
81.749 scanned protein domains

Full database

# tripeptides = 8.914.832

Coil database (LTS)

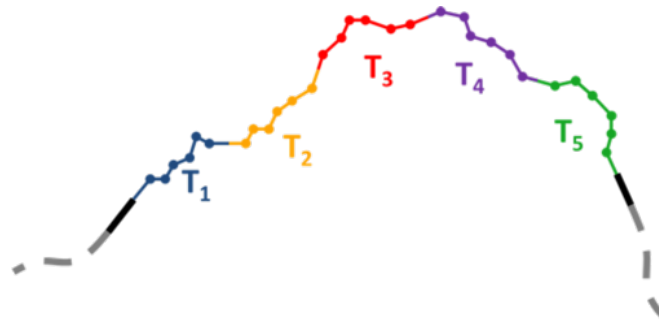
# tripeptides = 3.645.381



[Barozet *et al.*, Bioinformatics 2019]

## Main principle:

- Loop divided in 3-residue-long fragments (tripeptides)



- Database of tripeptide fragments from known structures

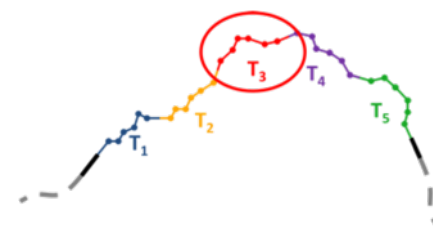


# A machine-learning approach to protein loop sampling

[Barozet *et al.*, Bioinformatics 2019]

## One iteration:

- Selection of a tripeptide for closure
- Iterative construction of the two loop ends, with backtracking

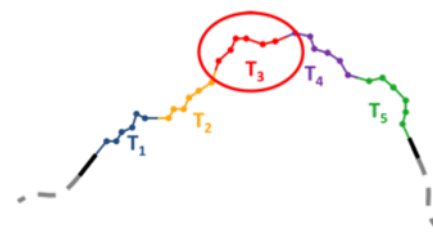


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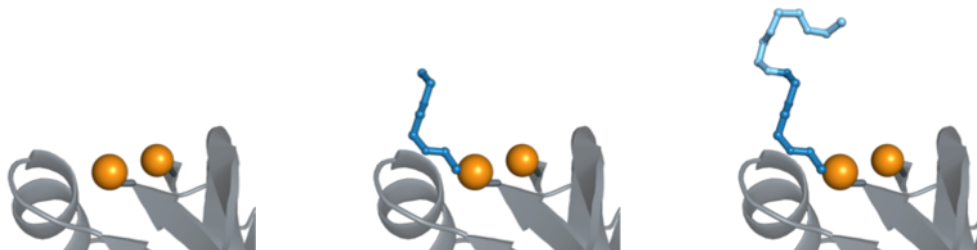
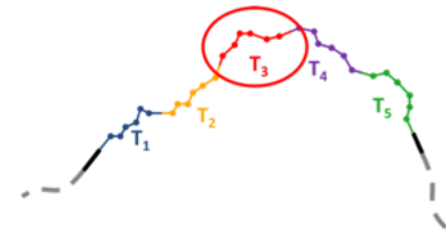


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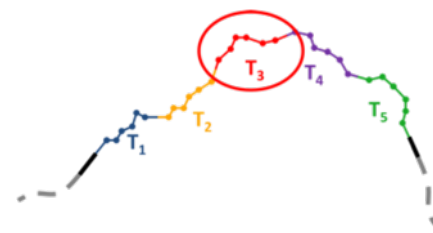


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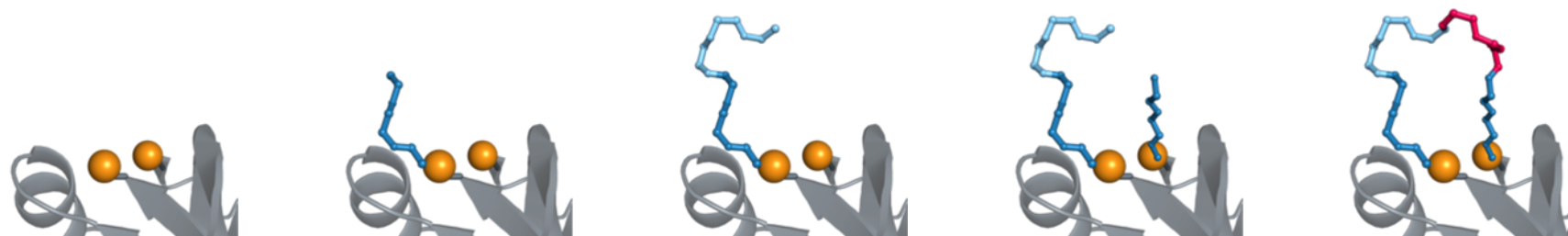
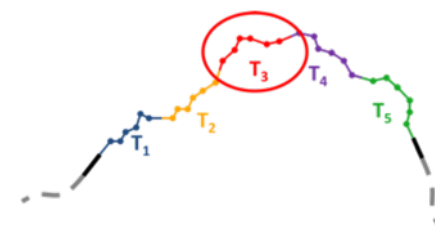


# A machine-learning approach to protein loop sampling

[Barozet *et al.*, Bioinformatics 2019]

## One iteration:

- Selection of a tripeptide for closure
- Iterative construction of the two loop ends, with backtracking
- Loop closure using **inverse kinematics** (IK)



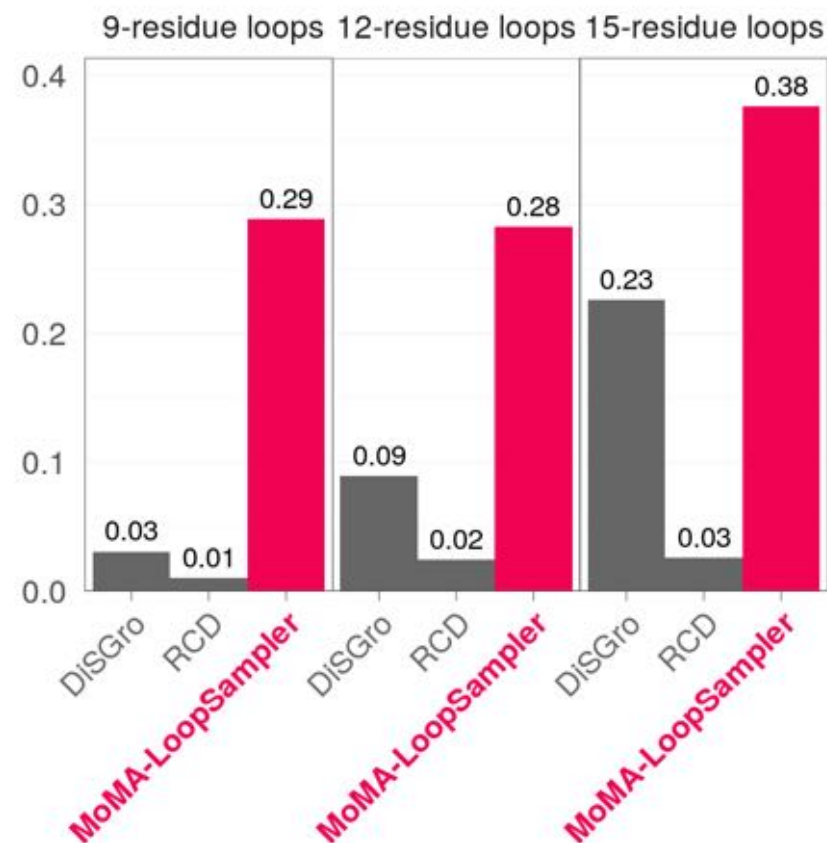
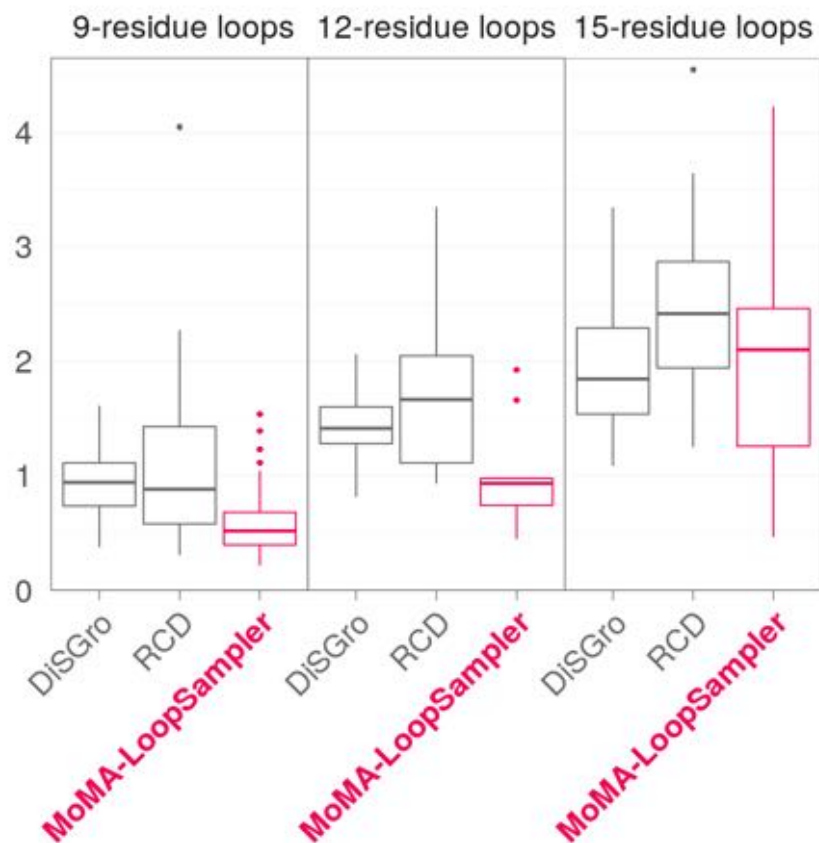
# A machine-learning approach to protein loop sampling

[Barozet *et al.*, Bioinformatics 2019]

## MoMA-LoopSampler yields better results than state-of-the-art methods

Min RMSD to native (Å)

Median running time (s)

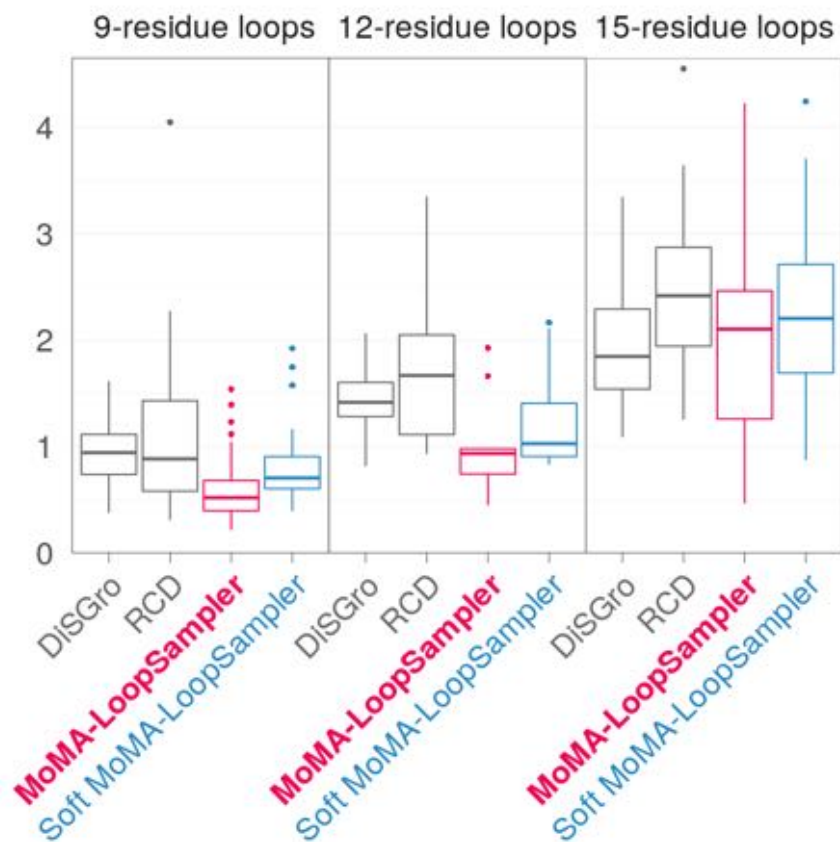


# A machine-learning approach to protein loop sampling

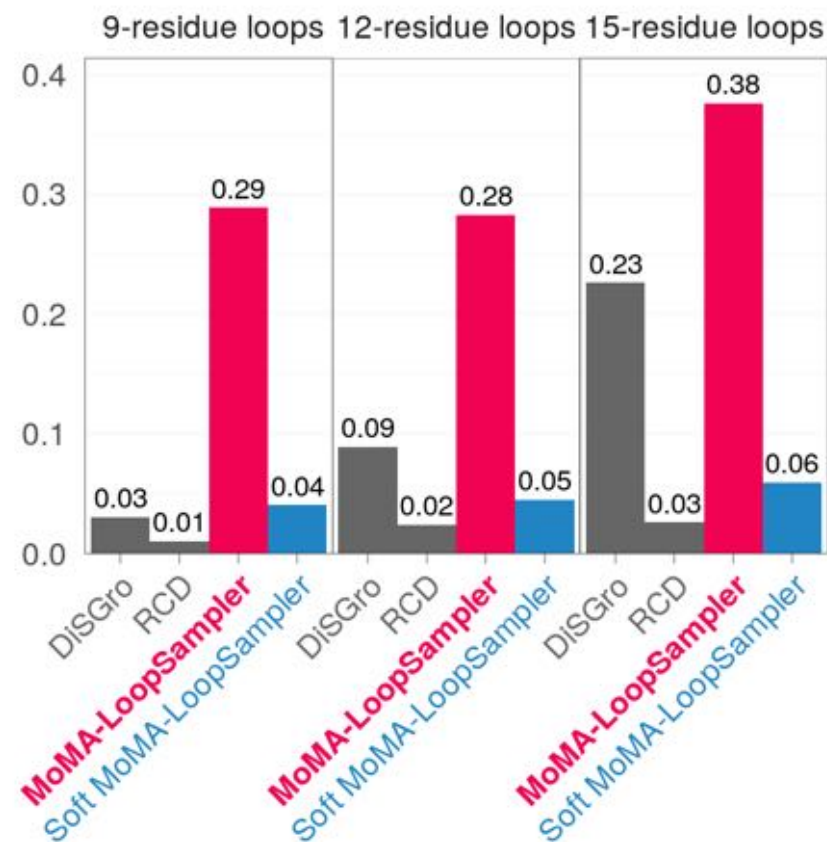
[Barozet *et al.*, Bioinformatics 2019]

Longer running times are due to the enforcement of stricter constraints

Min RMSD to native (Å)

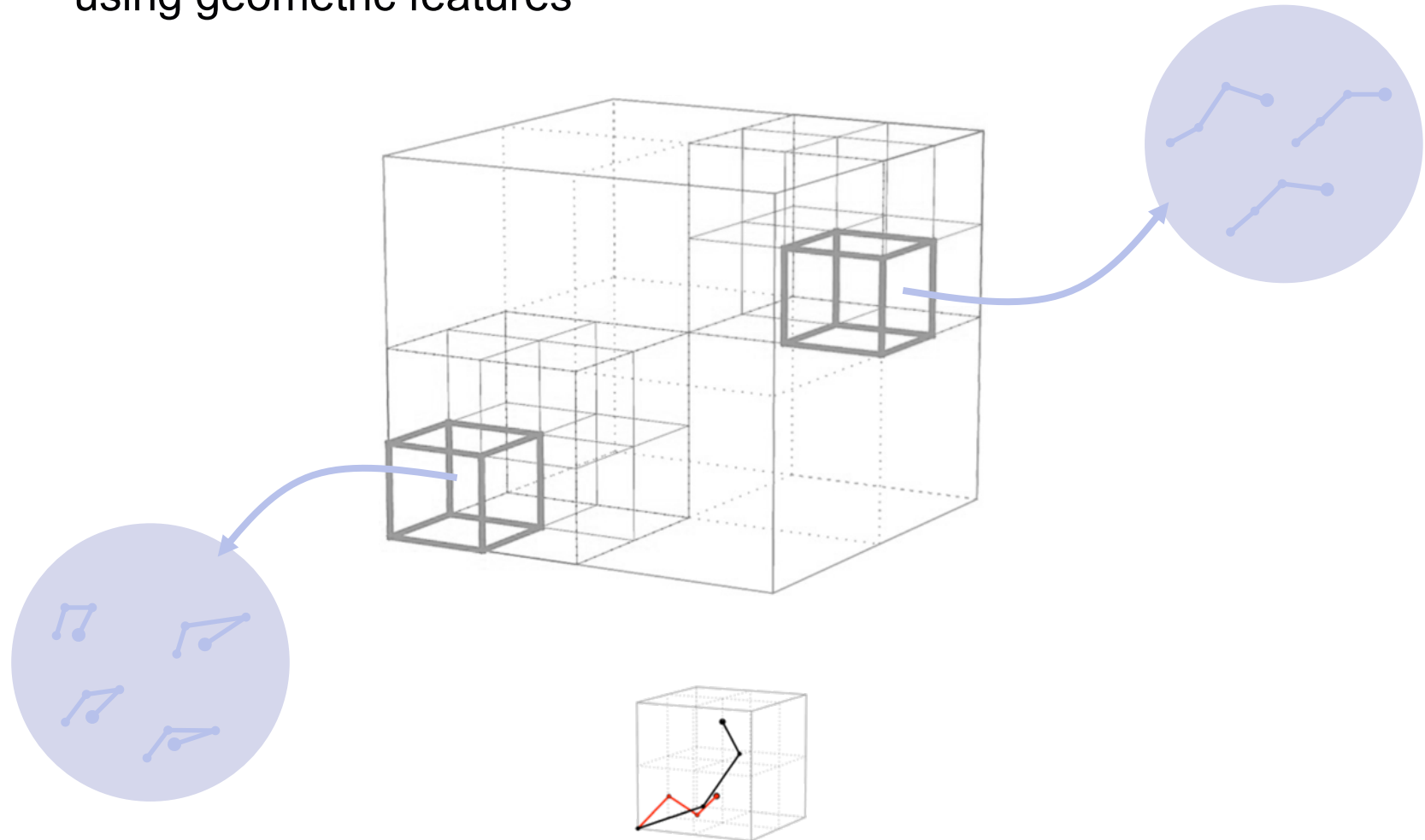


Median running time (s)



## A reinforcement-learning-based approach to enhance sampling

- Learning data-structure based on hierarchical classification using geometric features

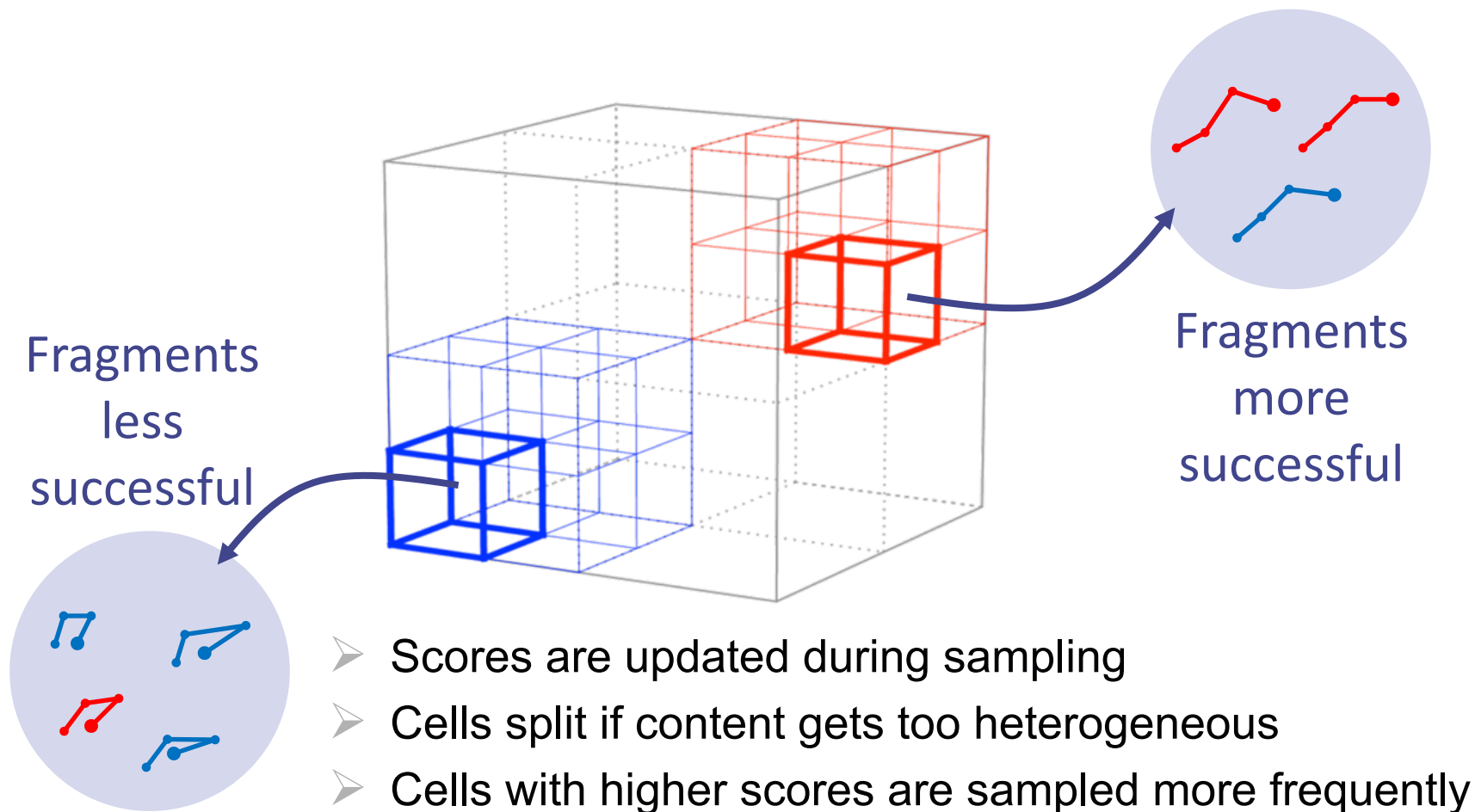


# A machine-learning approach to protein loop sampling

[Barozet *et al.*, Bioinformatics 2019]

## A reinforcement-learning-based approach to enhance sampling

- RL-based sampling heuristic



# A machine-learning approach to protein loop sampling

[Barozet *et al.*, Bioinformatics 2019]

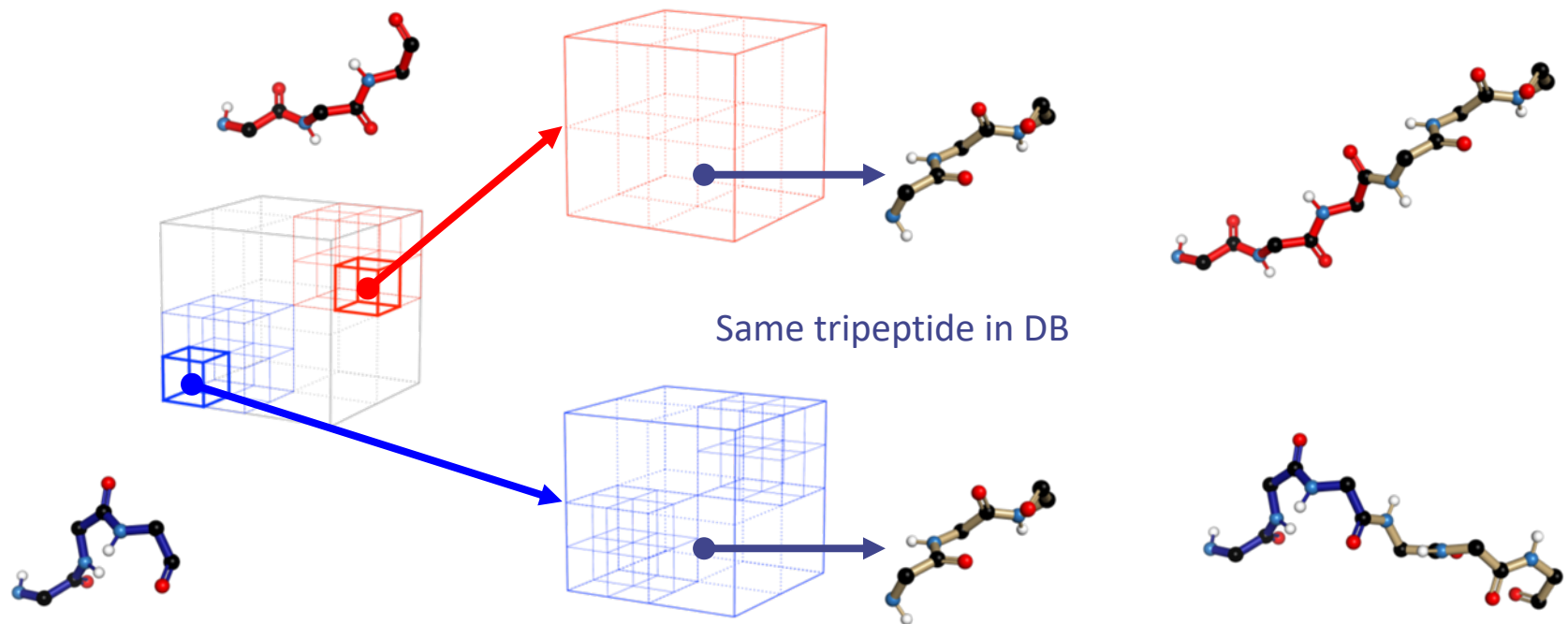
## A reinforcement-learning-based approach to enhance sampling

- The full learning structure involves chained trees

Tripeptide  $i$

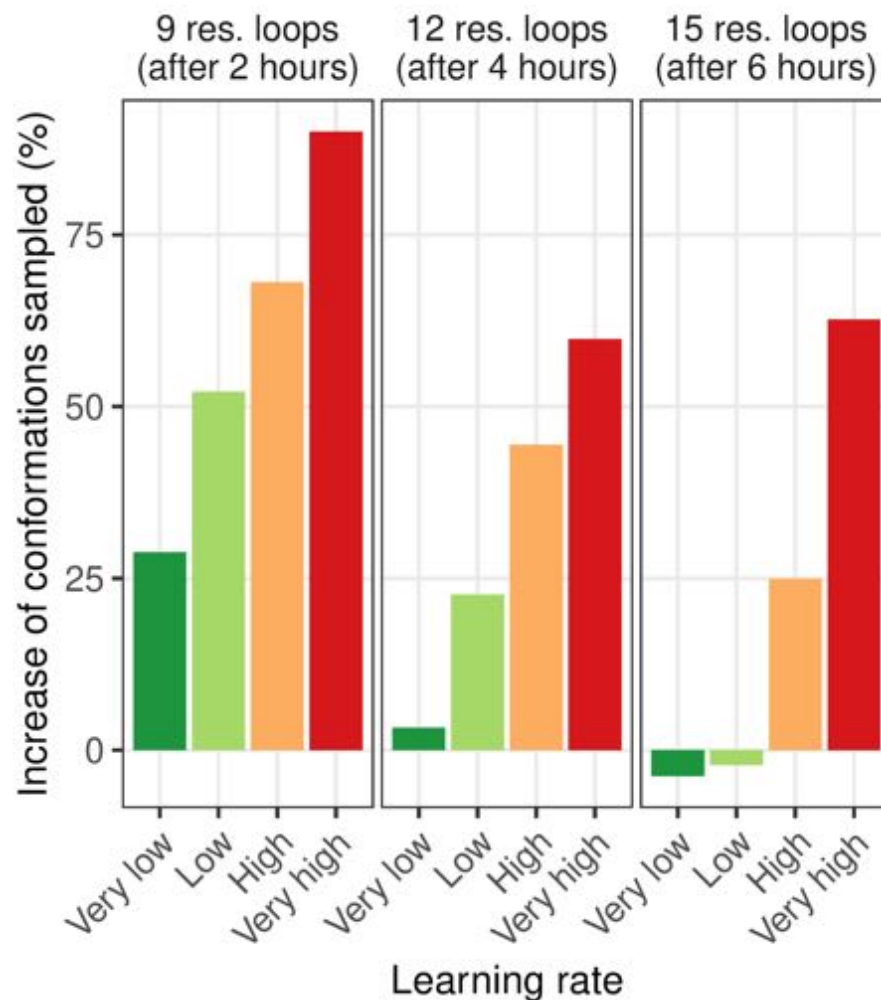
Tripeptide  $i+1$

Concatenation





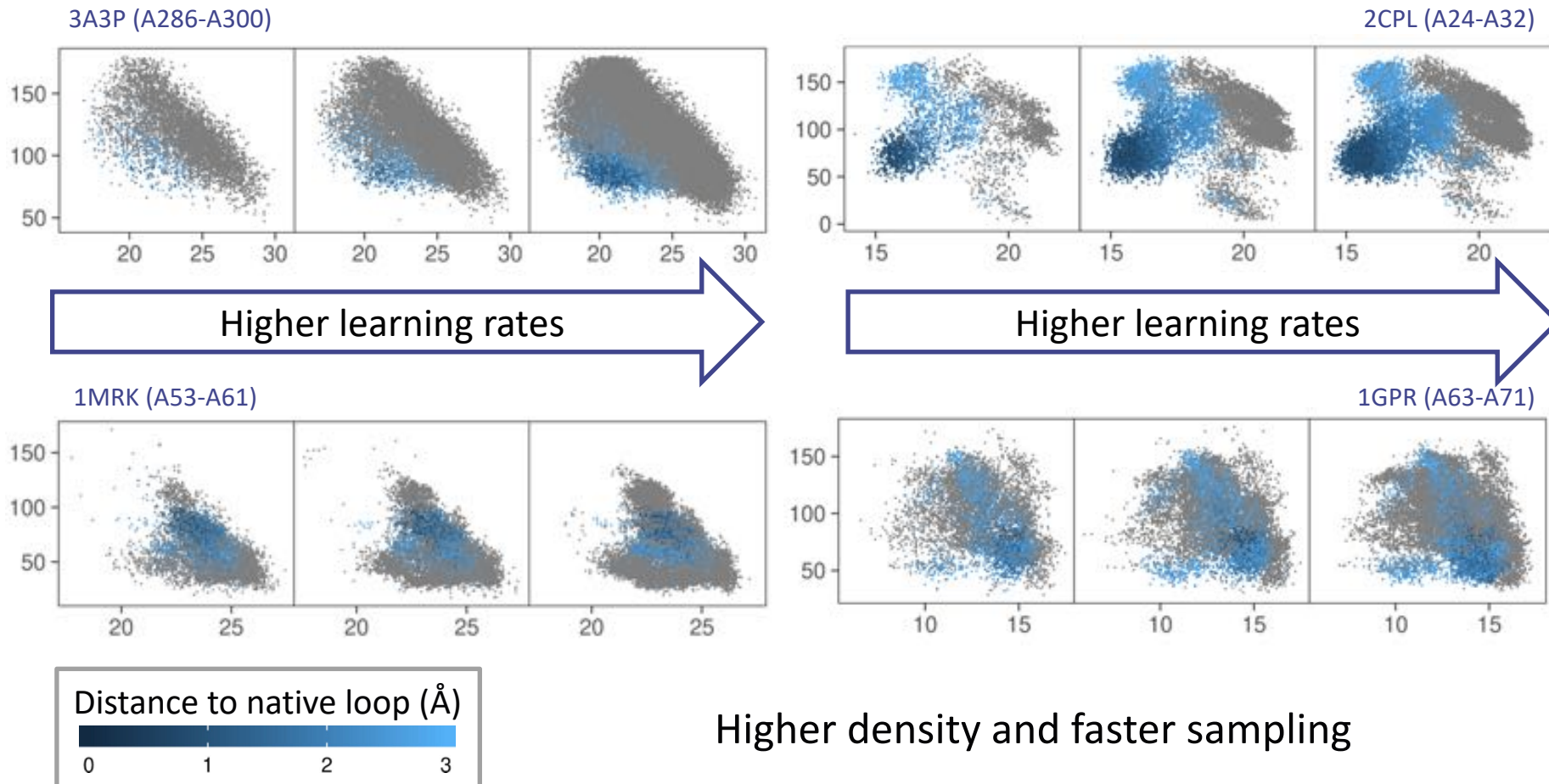
## Reinforcement learning speeds up sampling



# A machine-learning approach to protein loop sampling

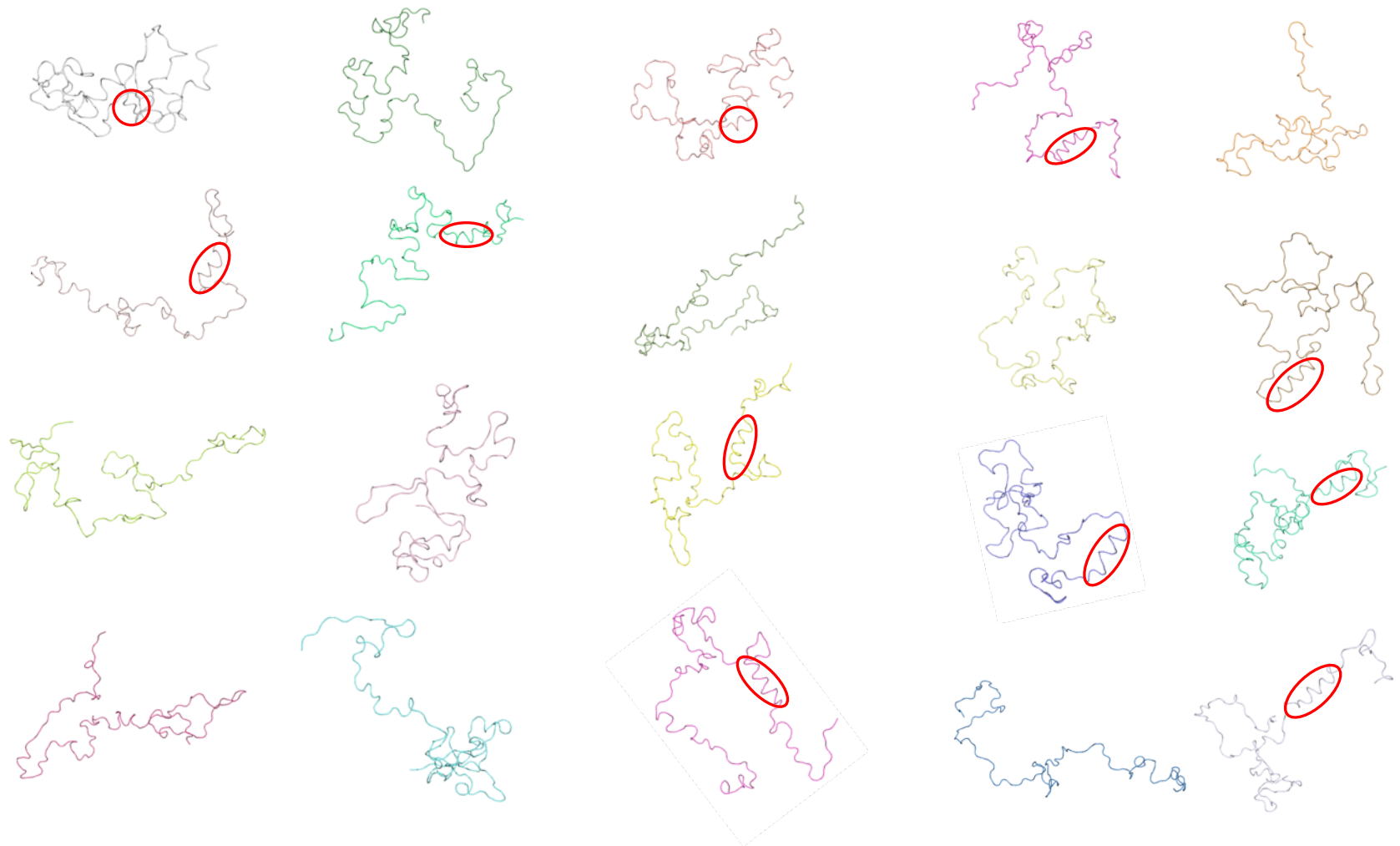
[Barozet *et al.*, Bioinformatics 2019]

## Reinforcement learning preserves diversity

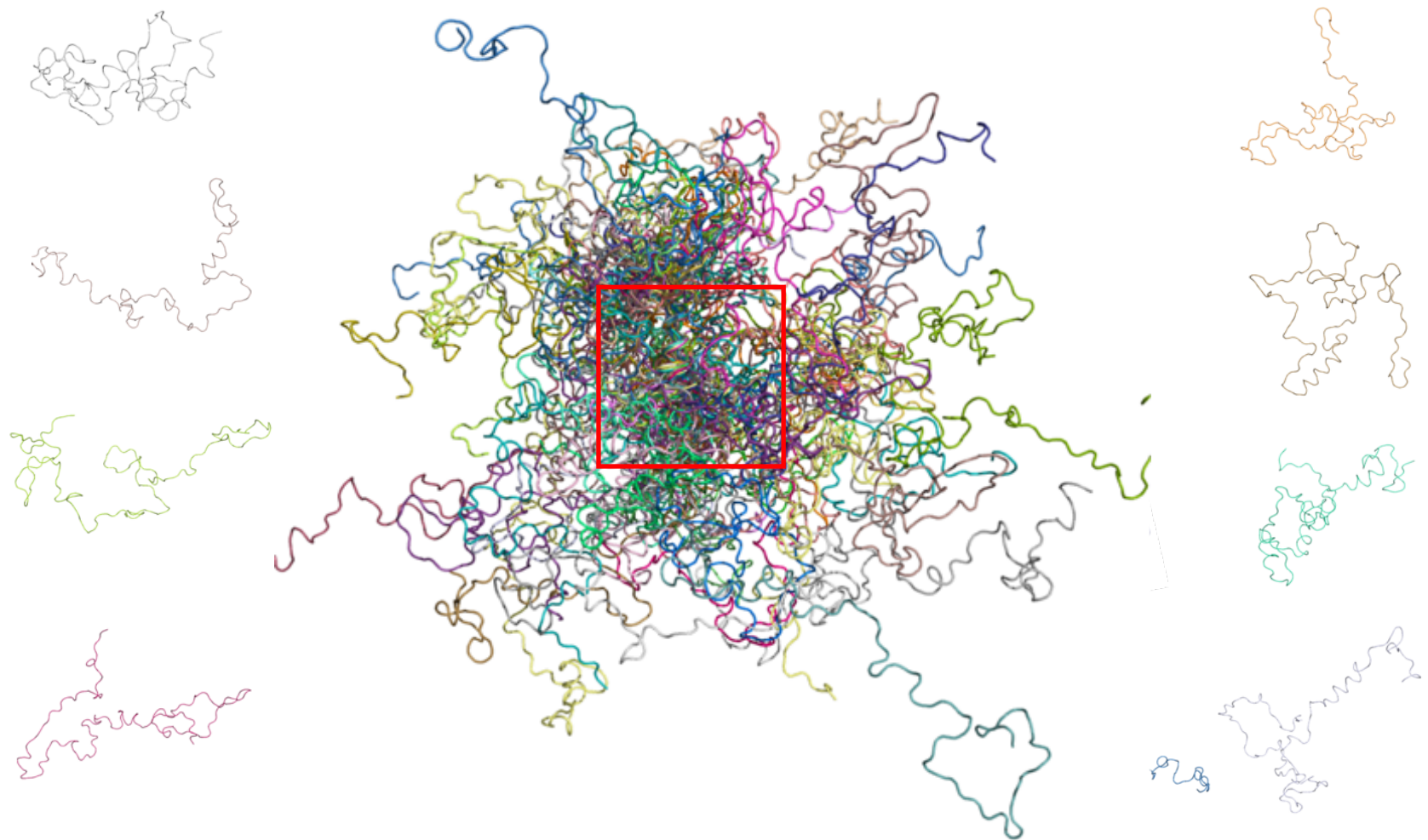


# Intrinsically Disordered Proteins (IDPs)

IDPs use to involve (partial) order inside structural disorder



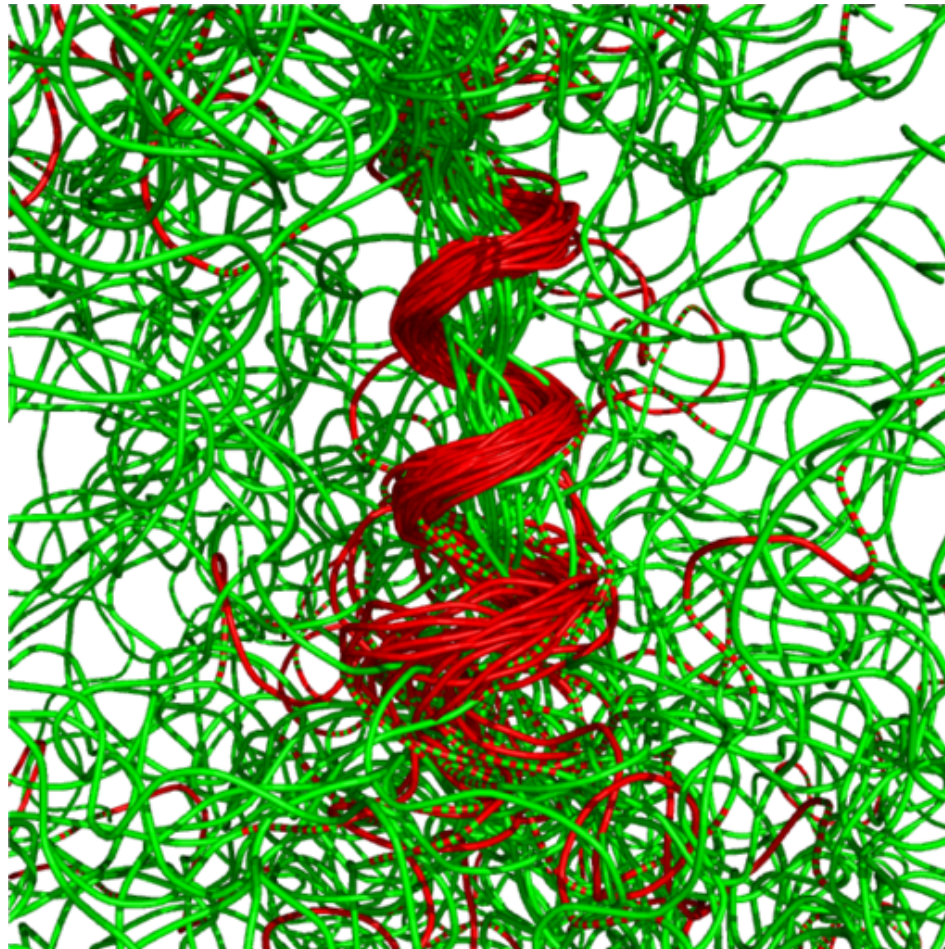
IDPs use to involve (partial) order inside structural disorder





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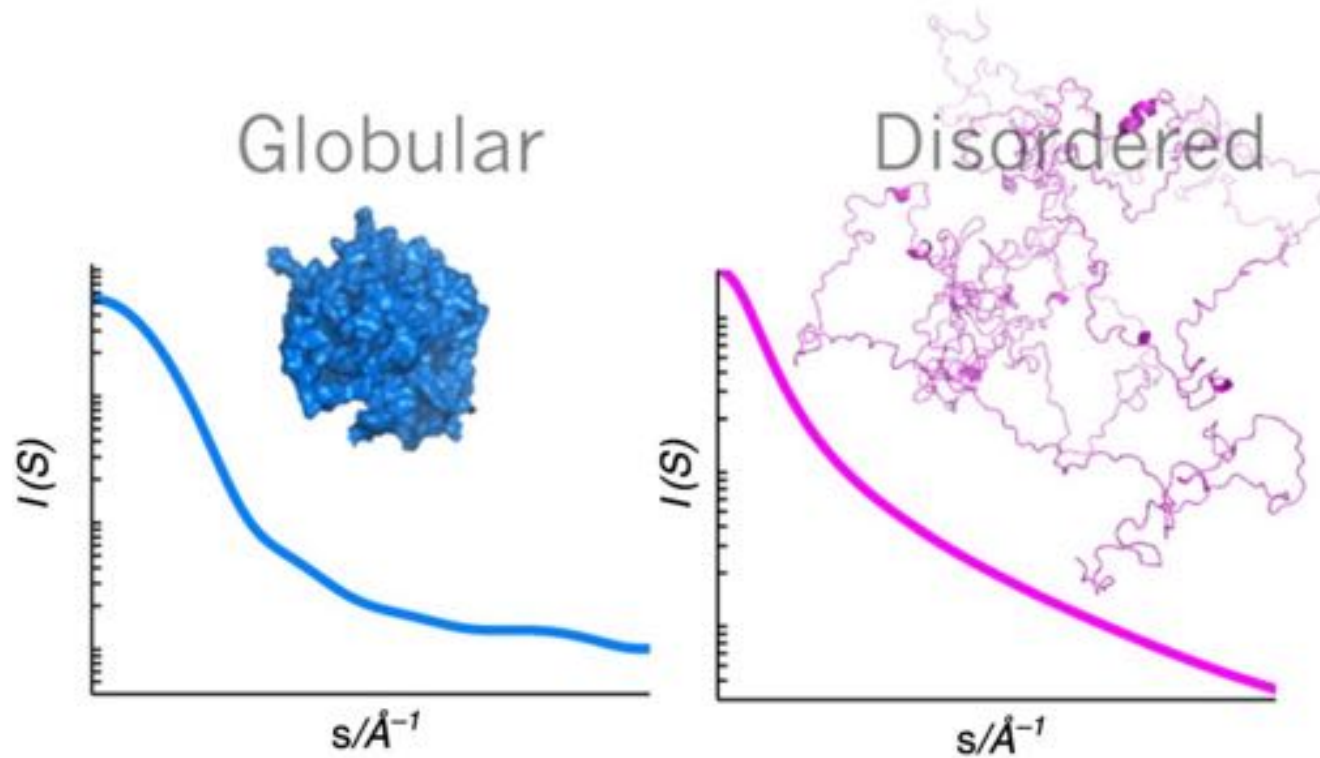
# Structural characterization of IDPs

*Collaboration with Pau Bernadó (CBS, Montpellier)*

Using small angle X-ray scattering (**SAXS**)

[Cordeiro *et al.*, COSB, 2017]

Information about overall shape



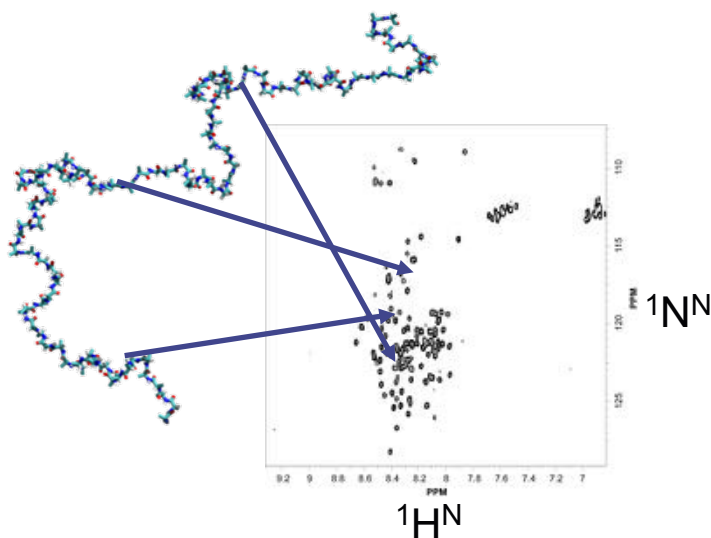


# Structural characterization of IDPs

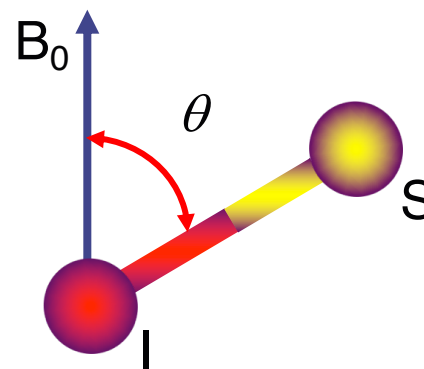
Collaboration with Pau Bernadó (CBS, Montpellier)

Using nuclear magnetic resonance (**NMR**)

Local information (at the single residue level)



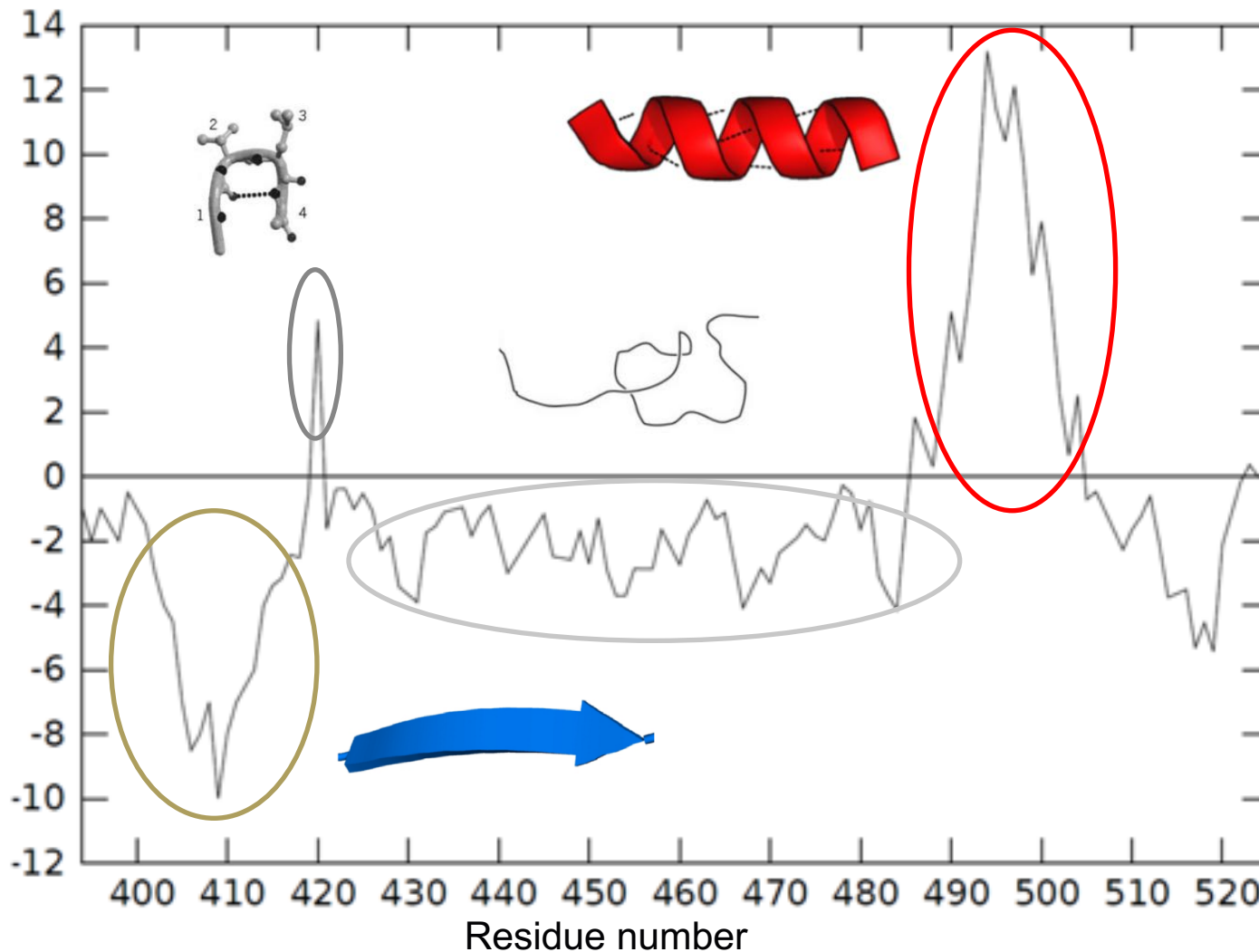
Each active nucleus can be identified



$$D_{IS}(\theta) = \frac{\hbar\gamma_I\gamma_S}{4\pi^2 r_{IS}^3} [1 - 3 \cos^2 \theta]$$

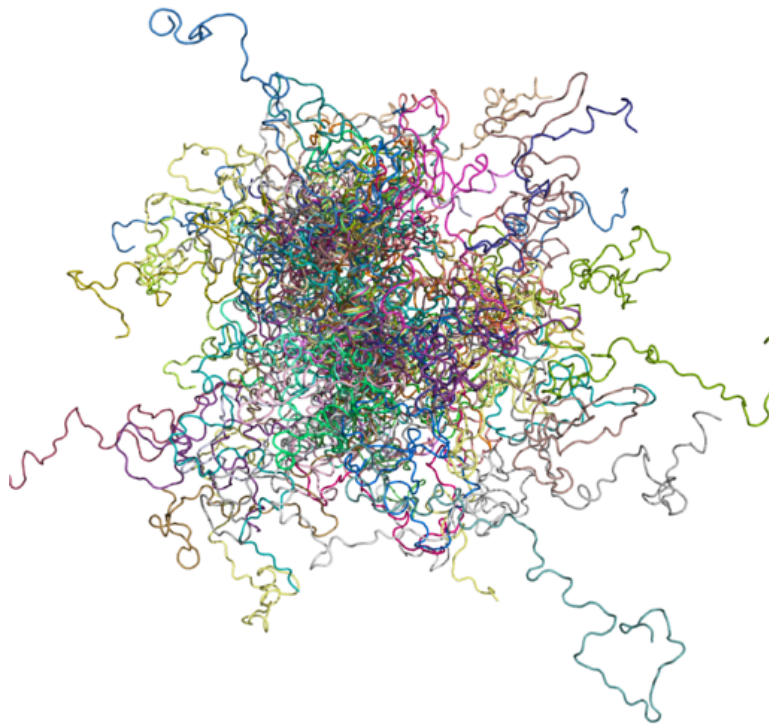
Residual dipolar couplings (**RDCs**) depend on the orientation of internuclear vectors relative to the alignment frame

## RDC profiles provide relevant structural information

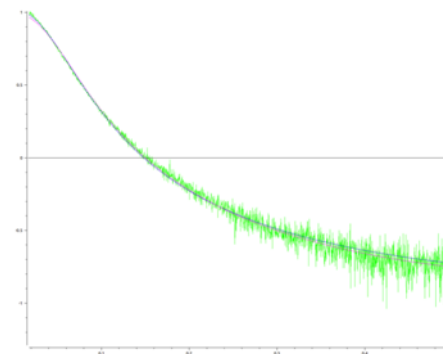


**Computational methods** are required to construct atomistic models fitting experimental data

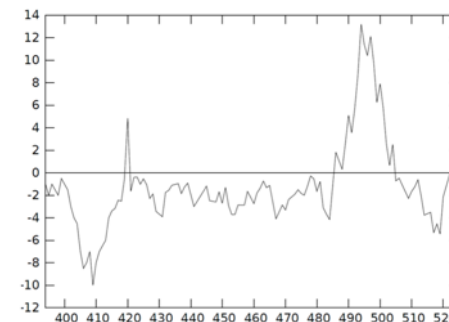
Conformational ensemble model



SAXS data



NMR data

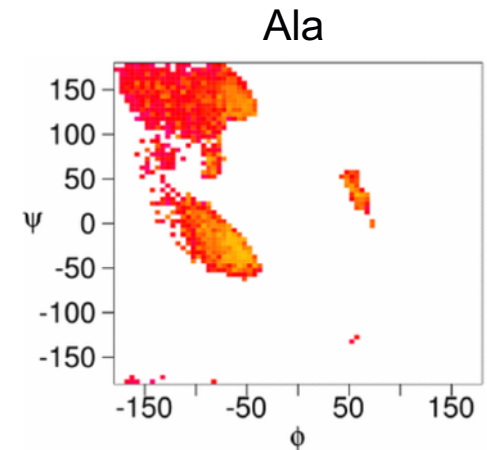


Flexible Meccano exploits statistical information at the **single residue level** to sample IDP's conformations

[Bernadó *et al.*, *PNAS*, 2005]

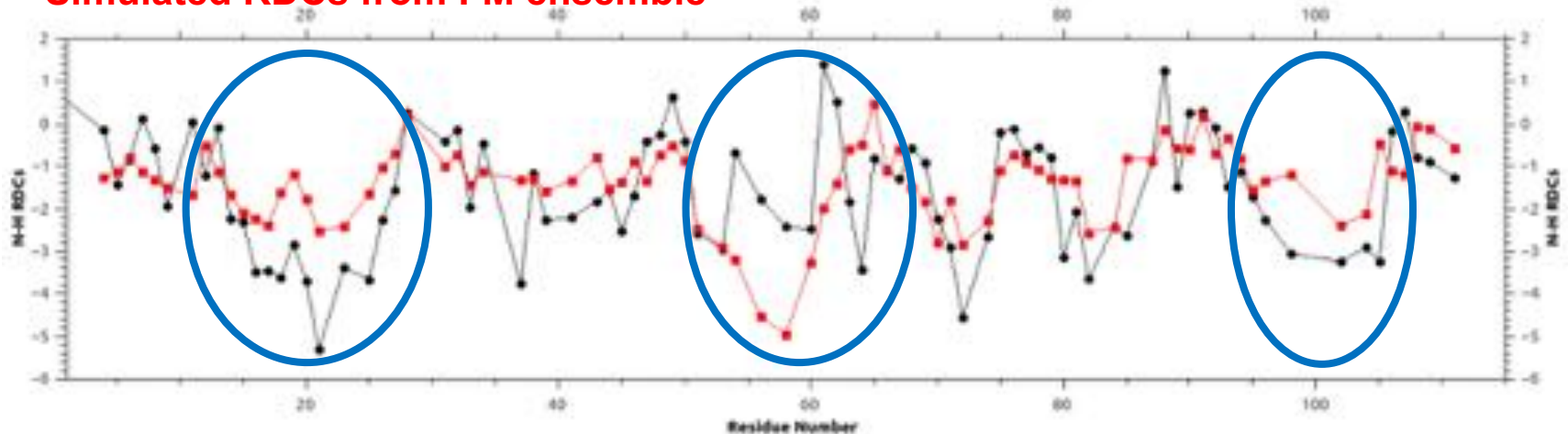
[Ozenne *et al.*, *Bioinformatics*, 2012]

- Accurate description of coil regions
- Fails to represent partially-structured regions



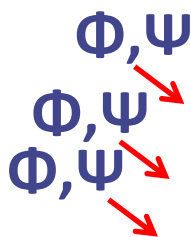
Experimental RDCs

Simulated RDCs from FM ensemble

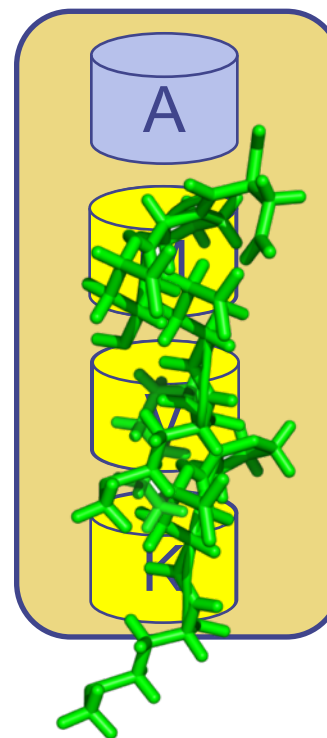


## Single-residue-based sampling strategy (SRS) (similar to Flexible-Meccano)

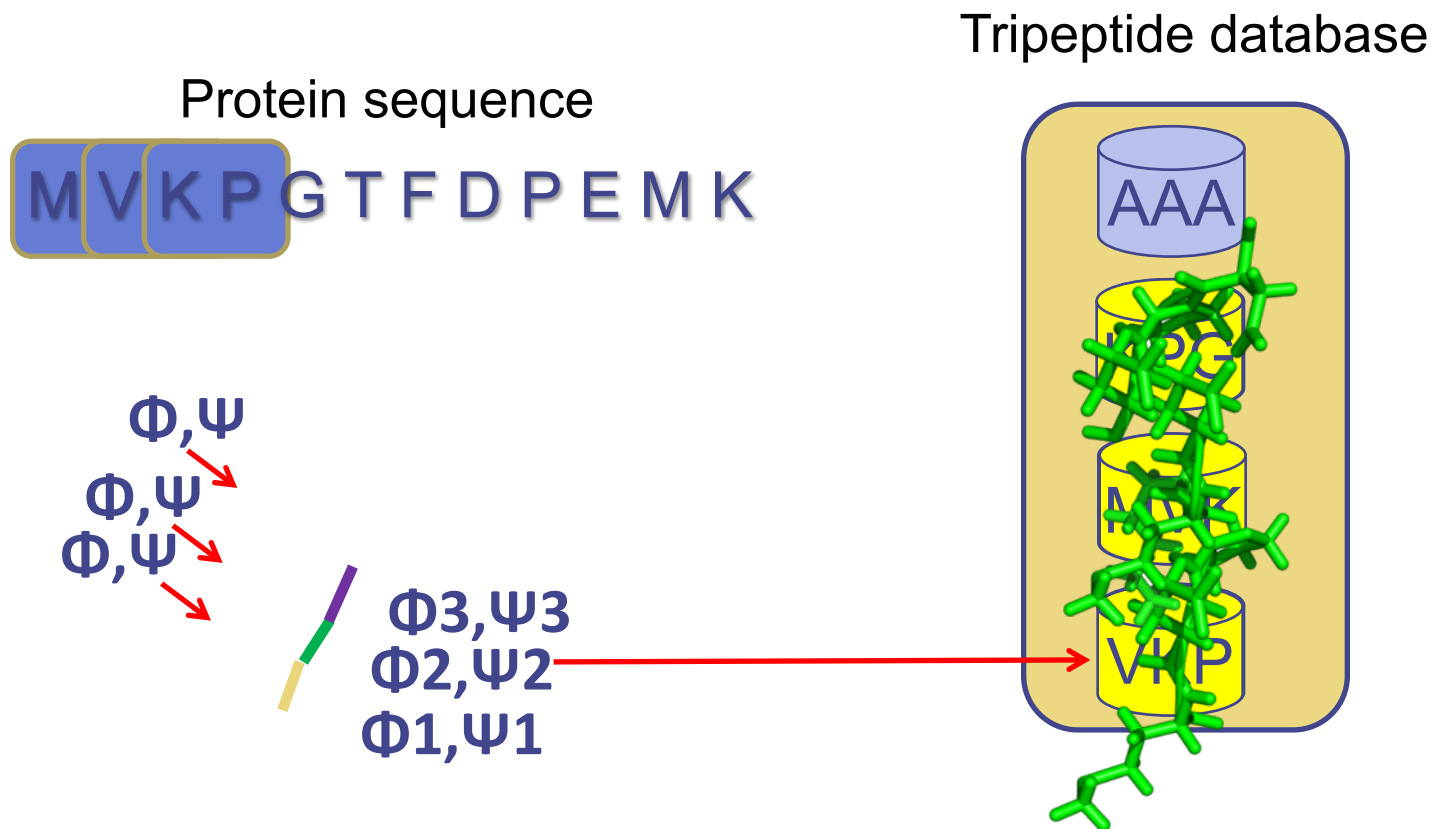
Protein sequence



Tripeptide database

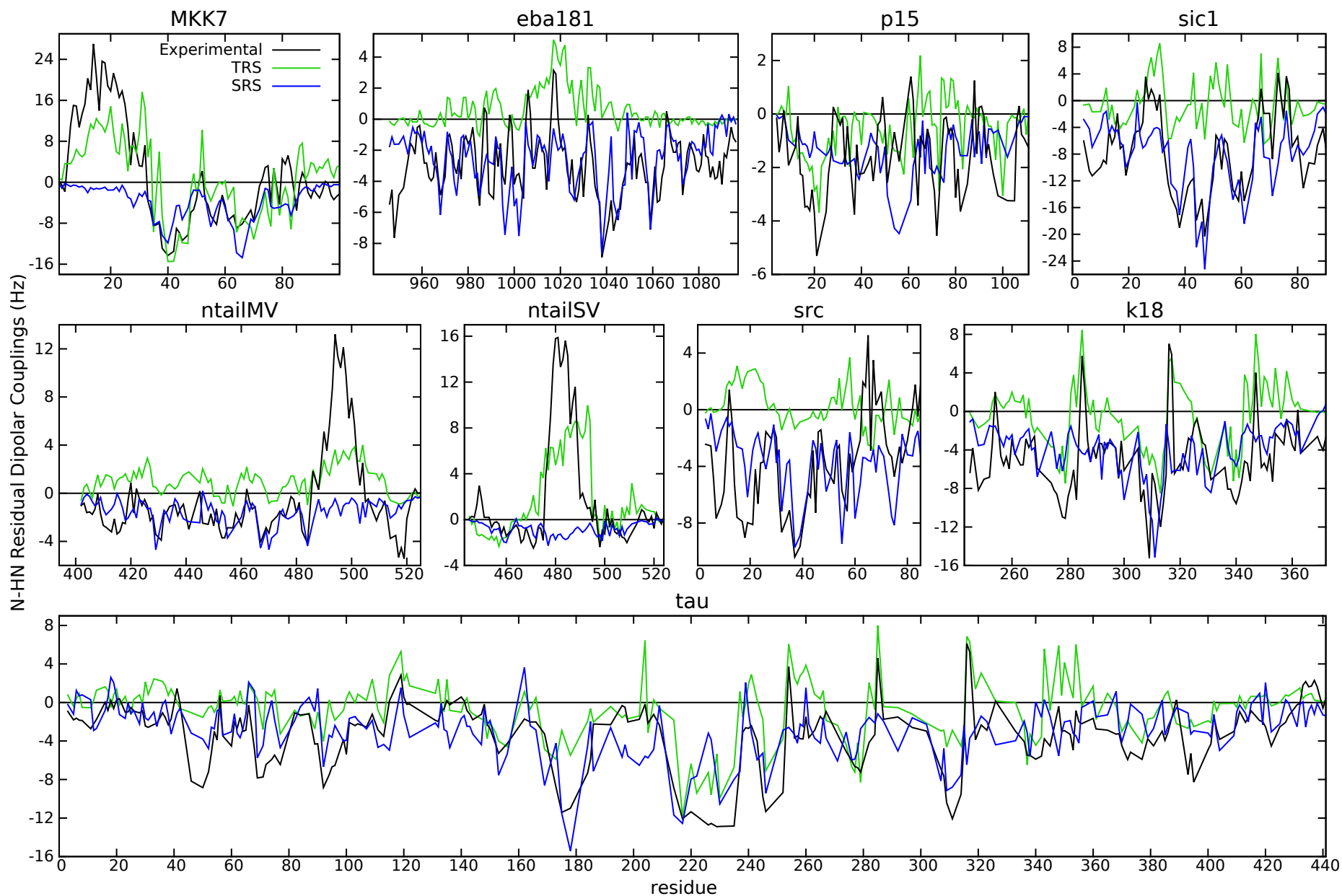


## Three-residue-based sampling strategy (TRS)

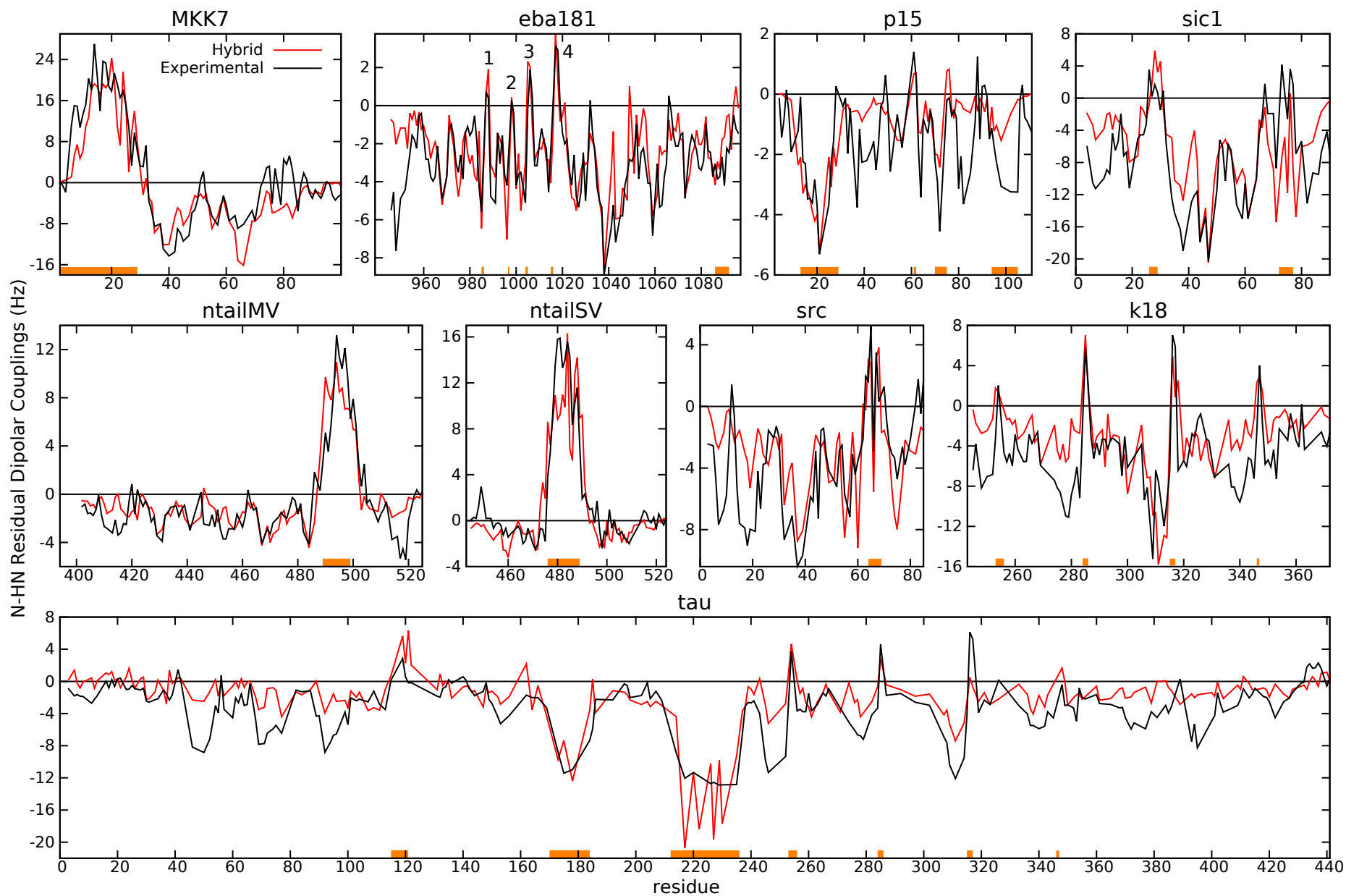




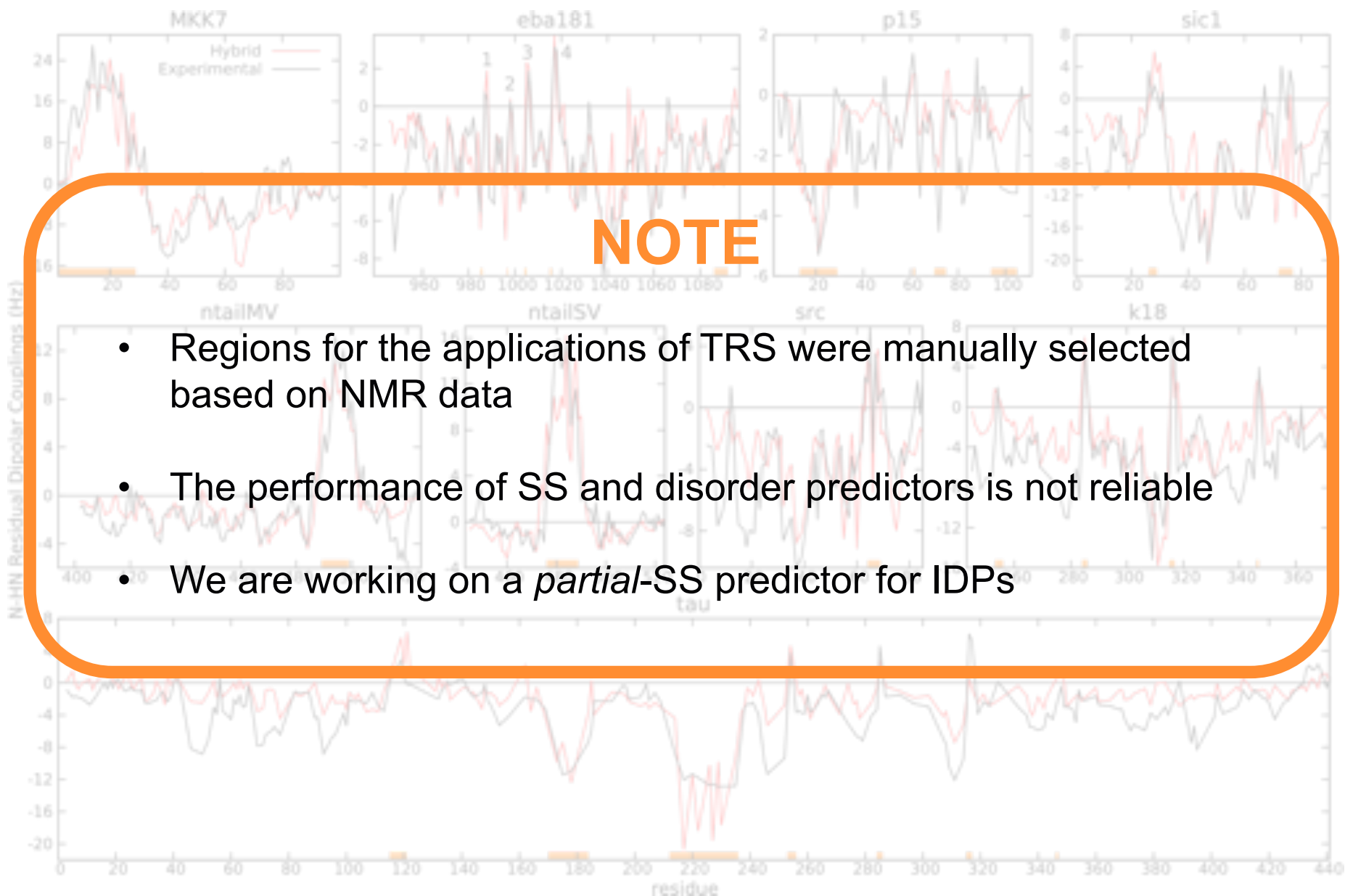
# Results **SRS** vs **TRS** : RDC profiles



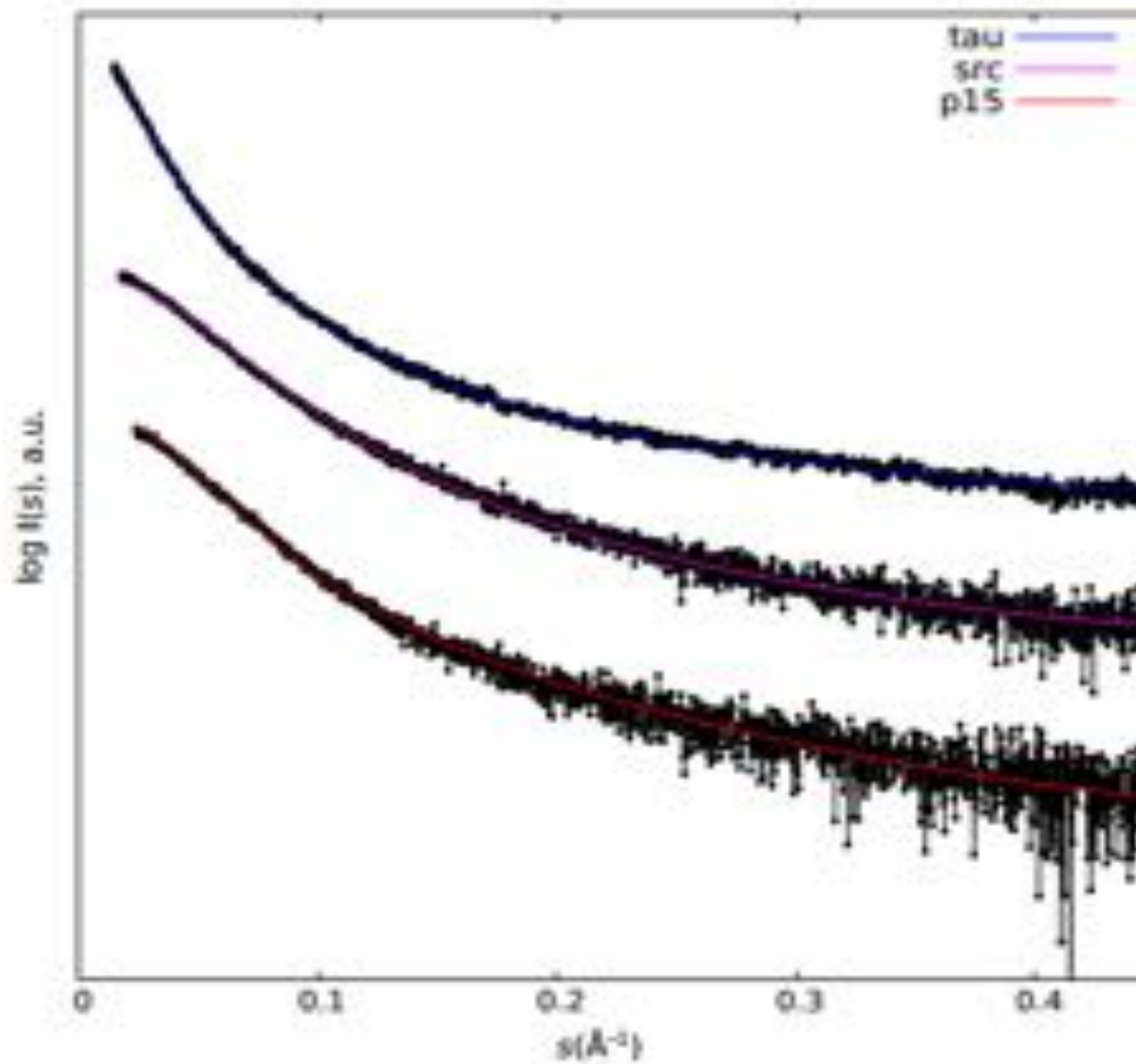
# Results **Hybrid SRS-TRS** : RDC profiles



# Results **Hybrid SRS-TRS** : RDC profiles



# Results **Hybrid SRS-TRS** : SAXS profiles



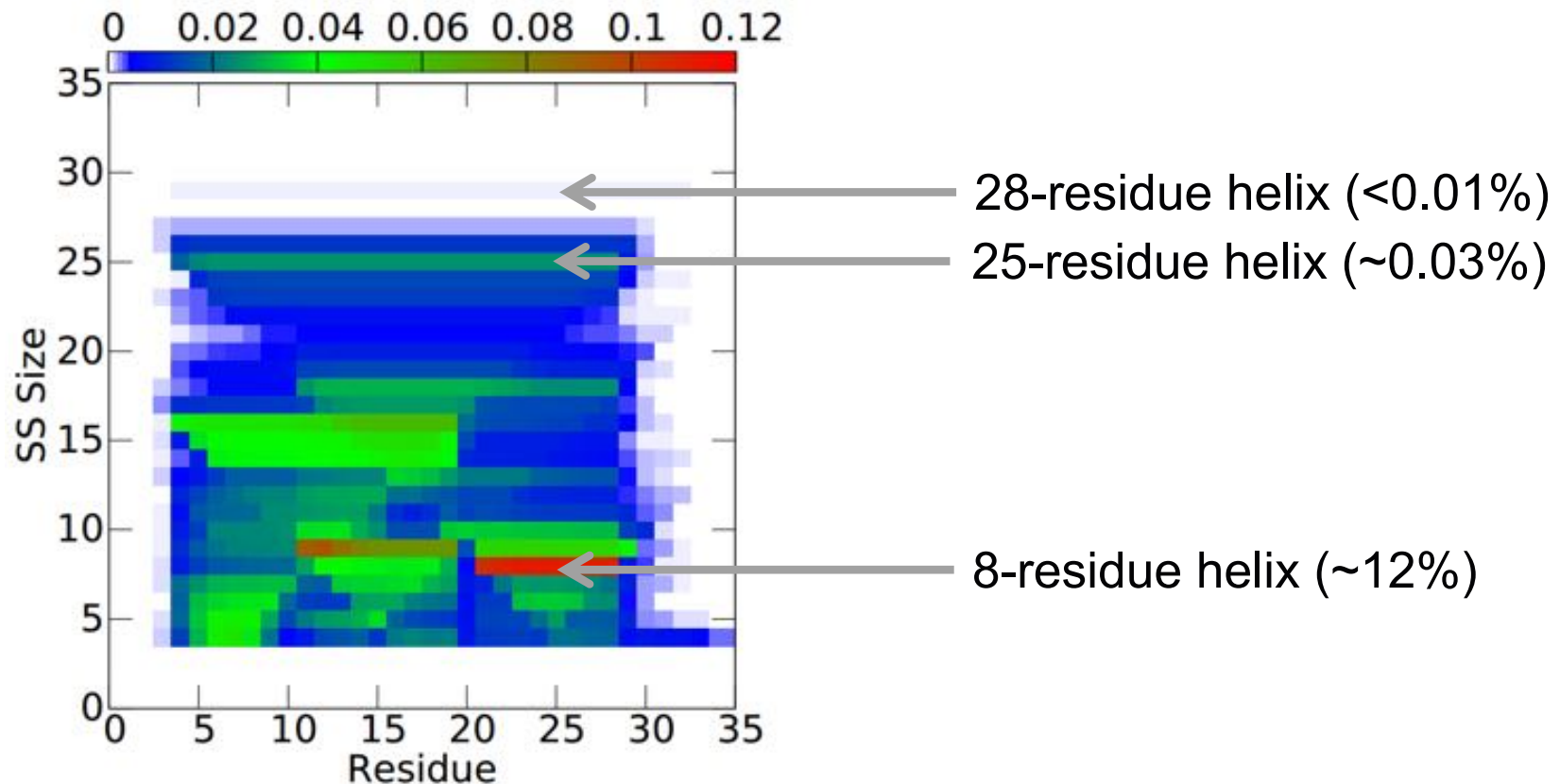
# Characterization of local secondary structural elements

[Estaña *et al.*, *Structure*, 2019]

N-terminal region of MKK7:

Partially-helical region, involving from 4 up to 28 residues

Secondary-structure-map (SS-map) [Iglesias *et al.*, 2013]



- **Folding of structural elements**

[Estaña *et al.*, *Molecules* 2019]

- **Secondary structure propensity prediction**

[Estaña *et al.*, *in preparation*]

- **IDP design**

ANR 2020 project proposal : LAAS, CBS, IMT



# Questions ?

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