

Inici > Semantic Scene Understanding with Large Language Models on Unmanned Aerial Vehicles

## Semantic Scene Understanding with Large Language Models on Unmanned Aerial Vehicles

**URL:** https://www.mdpi.com/2504-446X/7/2/114

Authors: de Curtò, J / de Zarzà, I / Calafate, Carlos

**Publication:** Drones

**Place Published: MDPI** 

Volume / Number / Pagination: 7 / 2 / 114

Paraules clau: Scene Understanding, Large Language Models, Visual Language Models, CLIP, GPT-3,

YOLOv7, UAV

Barcelona Supercomputing Center - Centro Nacional de Supercomputación

**Source URL** (retrieved on *3 abr 2025 - 21:56*): <a href="https://www.bsc.es/ca/research-and-development/publications/semantic-scene-understanding-large-language-models-unmanned">https://www.bsc.es/ca/research-and-development/publications/semantic-scene-understanding-large-language-models-unmanned</a>